

Statistical Methods in Particle Physics

4. Monte Carlo Methods

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Monte Carlo method

- Any method which solves a problem by generating suitable random numbers
- Useful for obtaining numerical solutions to problems which are too complicated to solve analytically
- The most common application of the Monte Carlo method is Monte Carlo integration

- Pioneers

- ▶ Enrico Fermi
- ▶ Stanislaw Ulam
- ▶ John von Neumann
- ▶ Nicholas Metropolis

<https://en.wikipedia.org>



Enrico Fermi



Stanislaw Ulam



J. von Neumann



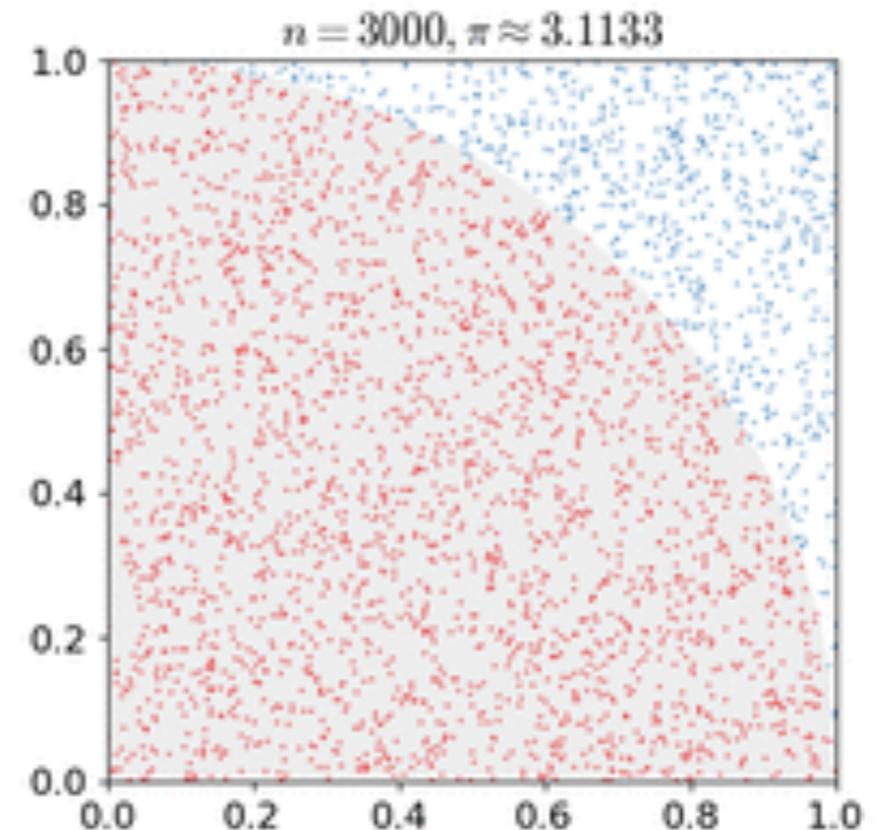
N. Metropolis

<http://mathworld.wolfram.com/MonteCarloMethod.html>

Monte Carlo method: Examples

[from Bohm, Zech: Introduction to Statistics and Data Analysis for Physicists]

- Area of a circle
- Volume of the intersection of a cone and a torus
 - ▶ Hard to solve analytically
 - ▶ Easy to solve by scattering points homogeneously inside a cuboid containing the intersect
- Efficiency of particle detection with a scintillator
 - ▶ Produced photons are reflected at the surfaces and sometime absorbed
 - ▶ Almost impossible to calculate analytically for different parameters like incident angle, particle energy, ...
 - ▶ Monte Carlo simulation is the only sensible approach



Pseudo-random numbers

- Principle: Use insignificant digits of an operation to generate next number
 - ▶ choose large integers λ and m , $\lambda < m$
 - ▶ choose integer $n_0 < m$ (“seed”)
 - ▶ uniformly distributed random numbers r_i :

$$n_{i+1} = \lambda n_i \bmod m$$

$$r_i = n_i / m, \quad r_i \in [0, 1]$$

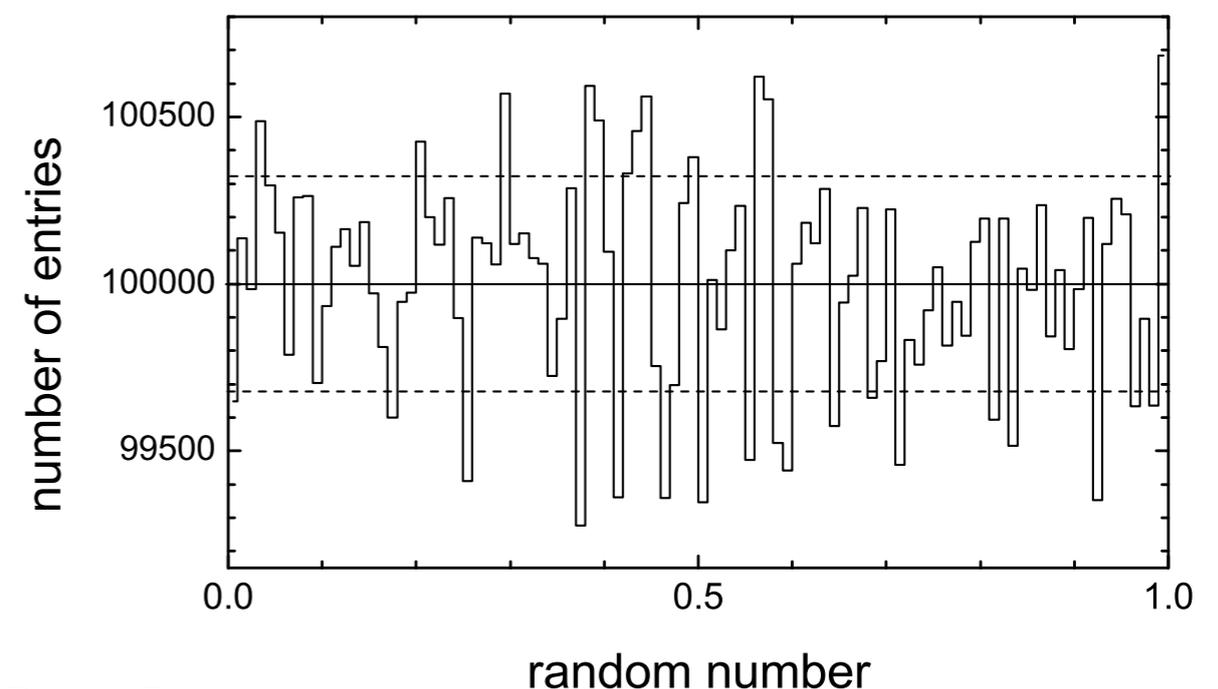
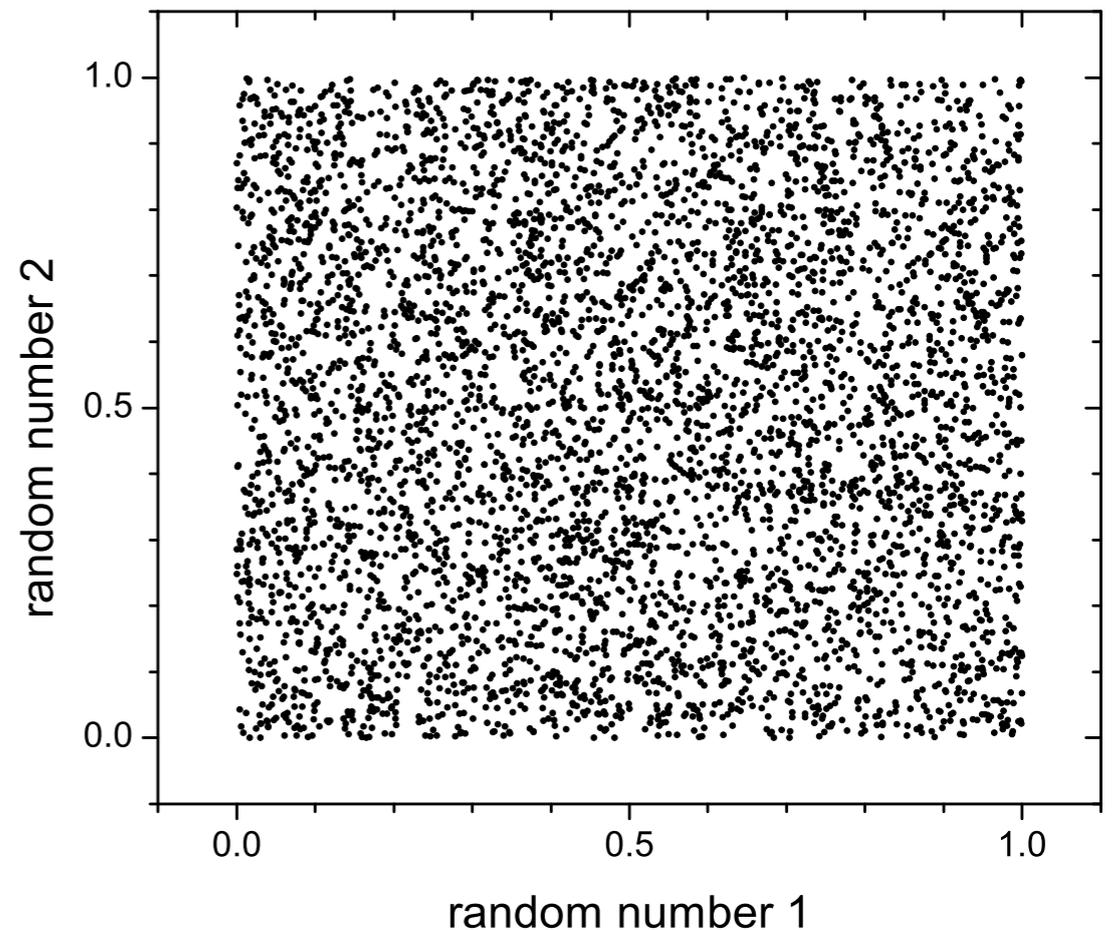
“Multiplicative linear congruential algorithm“
(period at maximum $m - 1$)

- *Mersenne twister*

- ▶ Invented 1997 by M. Matsomoto and T. Nishimura
- ▶ Sequence repeats after 2^{19937} calls, i.e., never ...

- Quality checks

- ▶ Frequency of occurrence
- ▶ Plot correlations between consecutive random numbers



Bohm, Zech:
http://www-library.desy.de/preparch/books/vstatmp_engl.pdf

Box-Muller algorithm for creating Gaussian distributed random numbers

1. Generate two uniformly distributed random numbers u_1 and u_2 in the range $[0,1]$

2. Set

$$\phi = 2\pi u_1, \quad r = \sqrt{-2 \ln u_2}$$

3. Then

$$z_1 = r \cos \phi \quad \text{and} \quad z_2 = r \sin \phi$$

are two independent rv's following a standard normal distribution

Why?

$$u_2(r) = e^{-\frac{r^2}{2}}$$

$$\frac{dp}{dr} = \frac{dp}{du_2} \cdot \left| \frac{du_2}{dr} \right| = e^{-\frac{r^2}{2}} r$$

$$dp = \underbrace{\frac{1}{2\pi} e^{-\frac{r^2}{2}} r dr d\phi}_{\text{2d standard normal distribution in polar coordinates}} = \underbrace{\frac{1}{2\pi} e^{-\frac{z_1^2+z_2^2}{2}} dz_1 dz_2}_{\text{2d standard normal distribution in cartesian coordinates}}$$

2d standard normal distribution in polar coordinates

2d standard normal distribution in cartesian coordinates

Random Numbers from distributions: Inverse transform method

Consider a distribution f from which we want to draw random numbers. Let $u(r)$ be the uniform distribution in $[0, 1]$:

$$\int_{-\infty}^x f(x') dx' = \int_0^{r(x)} u(r') dr' = r(x)$$

With $F(x)$ = cumulative distr.:

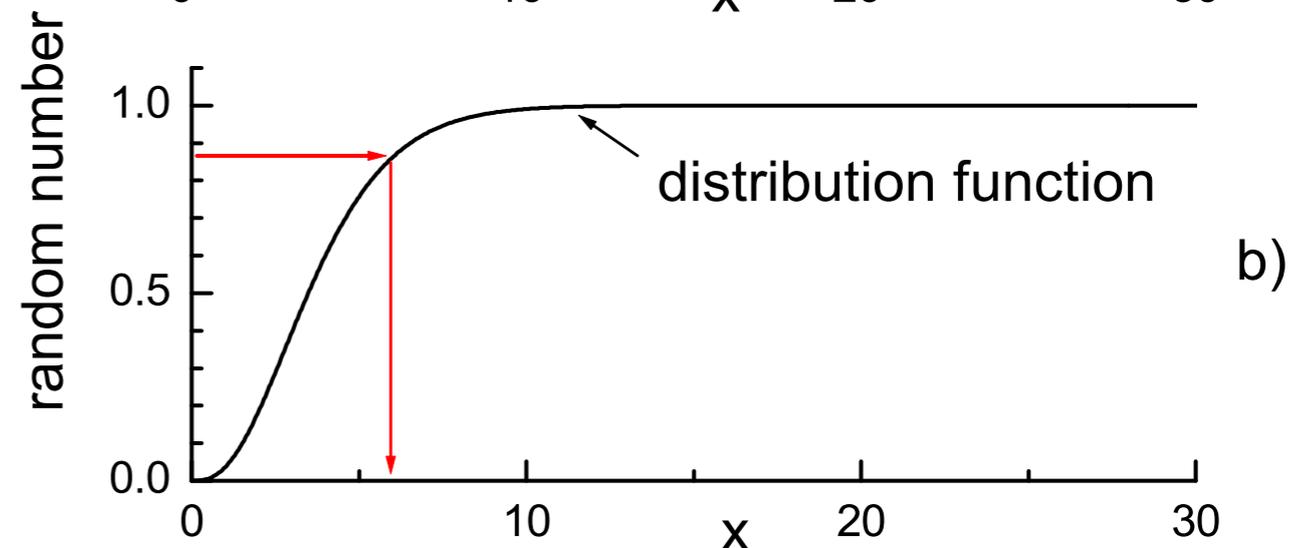
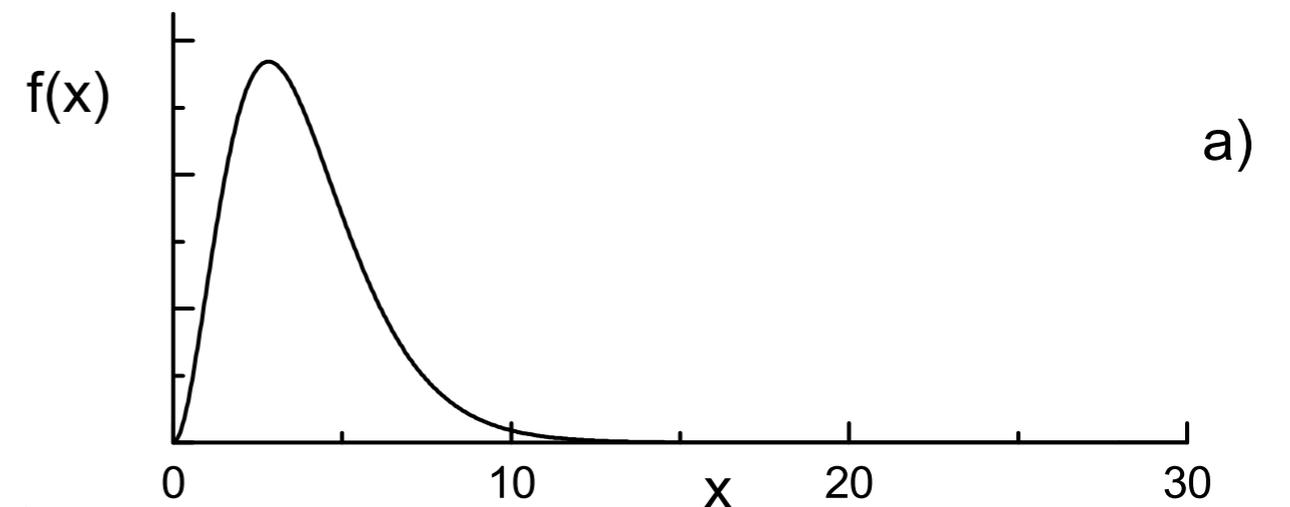
$$F(x) = r$$

We get the random number x from the inverse of the cumulative distribution:

$$x(r) = F^{-1}(r)$$

Bohm, Zech:

http://www-library.desy.de/preparch/books/vstatmp_engl.pdf



Cross check:

$$\frac{dp}{dx} = \underbrace{\frac{dp}{dr}}_{=1} \frac{dr}{dx} = \frac{dF(x)}{dx} = f(x) \quad \square$$

Example I

Linear function:

$$f(x) = 2x, \quad 0 \leq x \leq 1$$

$$F(x) = x^2 \quad \rightarrow \quad x = \sqrt{r}$$

Exponential:

$$f(x) = \gamma e^{-\gamma x}, \quad x \geq 0$$

$$F(x) = 1 - e^{-\gamma x} \quad \rightarrow \quad x = -\frac{\ln(1-r)}{\gamma}$$

One can store $F(x)$ as a histogram if there is no analytical solution, cf. root's `GetRandom()` function:

```
root [0] TF1 f("f", "x^3/(exp(x)-1)", 0., 15.);  
root [1] cout << f.GetRandom() << endl;  
13.9571
```

Inverse transform method using histograms in Python

```
def get_random(f, xmin, xmax, n_samples):  
    """Generate n_samples random numbers within range [xmin, xmax]  
    from arbitrary continuous function f  
    using inverse transform sampling  
    """  
  
    # number of points for which we evaluate F(x)  
    nbins = 10000  
  
    # indefinite integral F(x), normalize to unity at xmax  
    x = np.linspace(xmin, xmax, nbins+1)  
    F = integrate.cumtrapz(f(x), x, initial=0)  
    F = F / F[-1]  
  
    # interpolate F^{-1} and evaluate it for  
    # uniformly distributed rv's in [0,1[  
    inv_F = interpolate.interp1d(F, x, kind="quadratic")  
    r = np.random.rand(n_samples)  
    return inv_F(r)
```

[\[random numbers from distribution.ipynb\]](#)

Example II: Uniform points on a sphere

$$\frac{dp}{d\Omega} = \frac{dp}{\sin \theta d\theta d\phi} = \text{const} \equiv k$$

$$\frac{dp}{d\theta d\phi} = k \sin \theta \equiv f(\phi)g(\theta)$$

Distributions for θ and ϕ :

$$f(\phi) \equiv \frac{dp}{d\phi} = \text{const} = \frac{1}{2\pi}, \quad 0 \leq \phi \leq 2\pi$$

$$g(\theta) \equiv \frac{dp}{d\theta} = \frac{1}{2} \sin \theta, \quad 0 \leq \theta \leq \pi$$

Calculating the inverse of the cumulative distribution we obtain:

$$\phi = 2\pi r_1$$

$$\theta = \arccos(1 - 2r_2) \quad [\text{as } G(\theta) = \frac{1}{2}(1 - \cos \theta)]$$

Upshot: ϕ and $\cos \theta$ need to be distributed uniformly

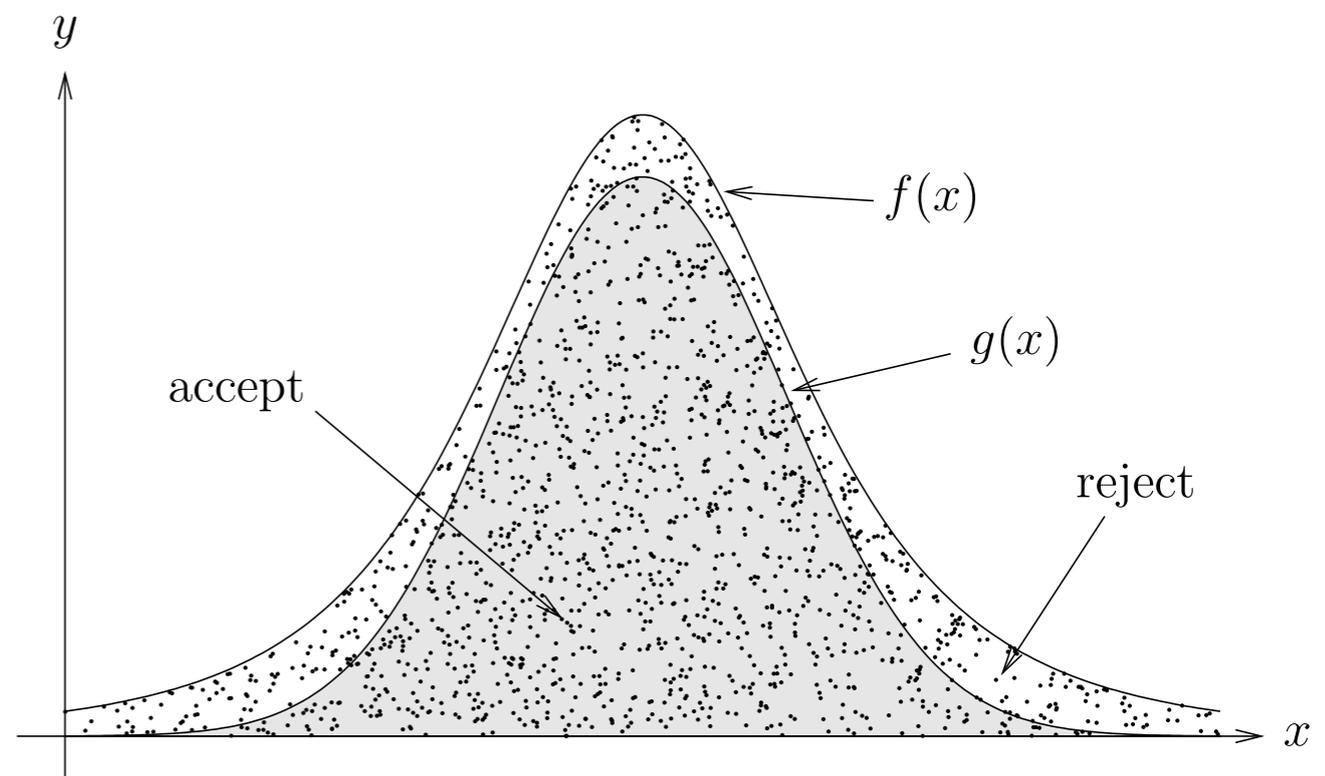
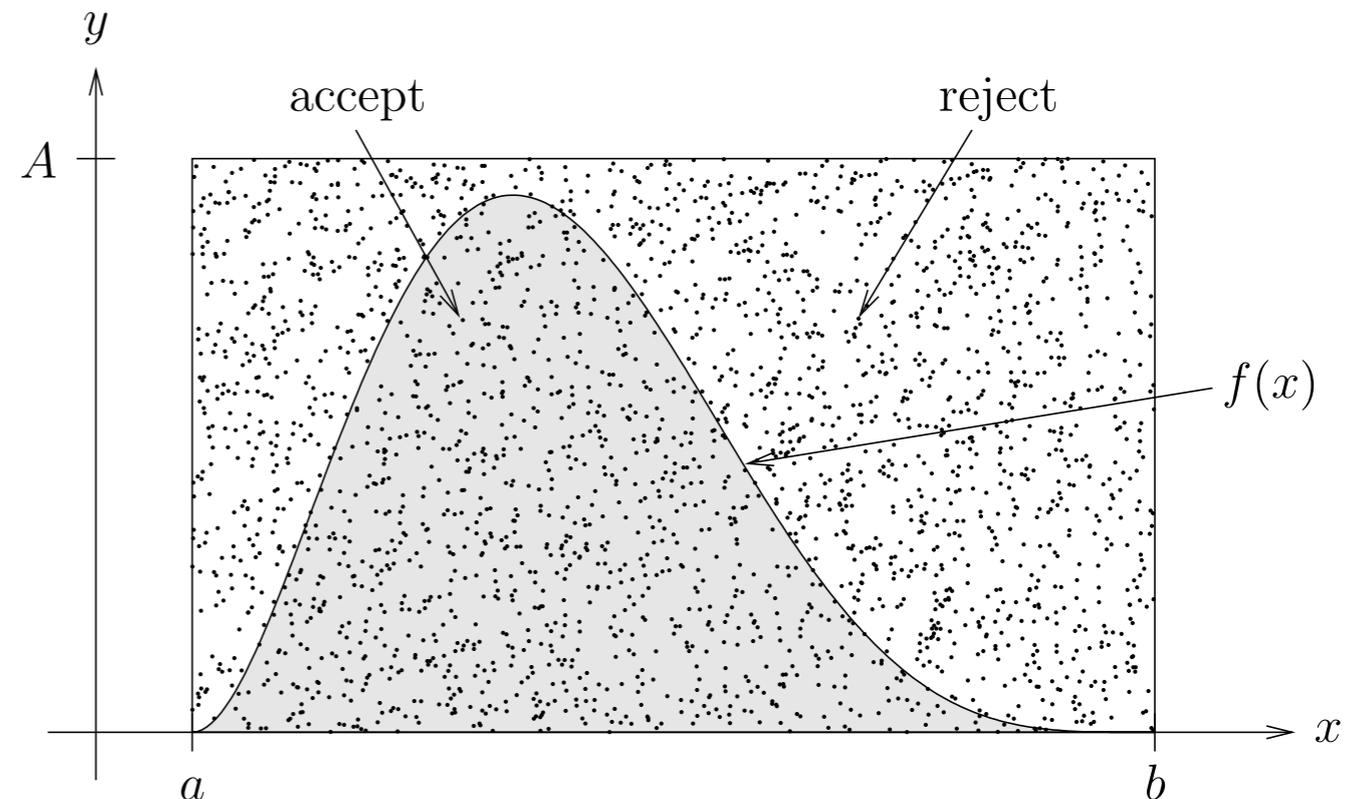
Random numbers from distributions: Acceptance-rejection method

■ Algorithm

- ▶ Generate random number x uniformly between a and b
- ▶ Generate second random y number uniformly between 0 and A
- ▶ Accept x if $y < f(x)$
- ▶ Repeat many times

■ The efficiency of this algorithm can be quite small

■ Improvement possible by choosing a majorant, i.e., a function which encloses $g(x)$ and whose integral is known ("importance sampling")



Random numbers from multivariate Gaussian (1)

Random number from multivariate normal distribution $f(\vec{x}; \vec{\mu}, V)$:

1. Calculate the Cholesky decomposition $V = AA^T$
2. Draw z_1, z_2, \dots, z_n from the standard normal distribution $N(0,1)$ and let $\vec{z} = (z_1, z_2, \dots, z_n)$
3. Output $\vec{x} = \vec{\mu} + A\vec{z}$

Cholesky decomposition:

A symmetric positive-definite matrix V can be written as

$$V = AA^T$$

where A is a real lower triangular matrix with positive diagonal entries.

Random numbers from multivariate Gaussian (2)

[random numbers mv normal distr.ipynb]

```
# example: 2d normal distribution
mu = np.array([0., 0.]) # mean
cov = np.array([[1, 0.8], [0.8, 1]]) # cov. matrix

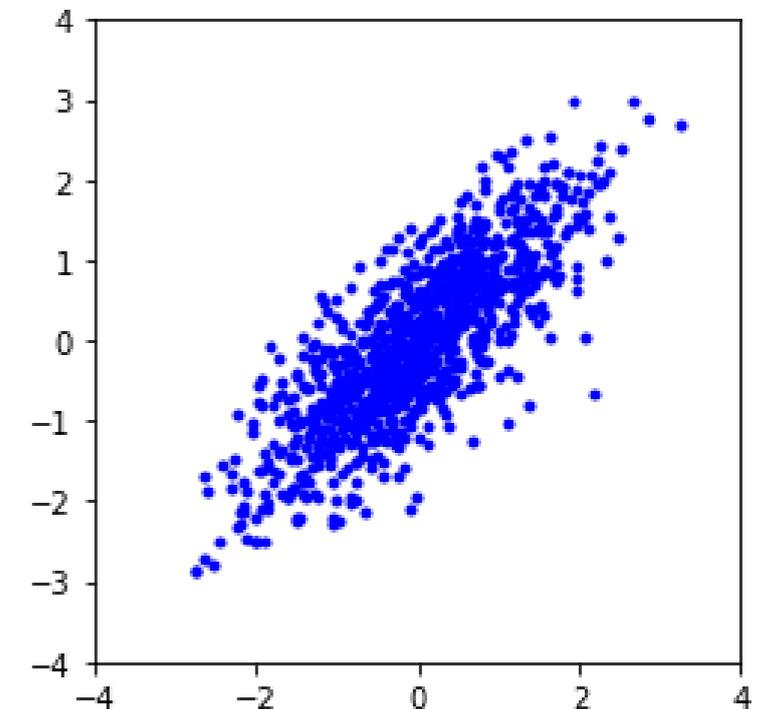
# Cholesky decomposition, A = lower triangular matrix
A = np.linalg.cholesky(cov)

# number of random vectors
n = 1000

# random numbers following standard normal distr.
# Ndim rows, N columns (here Ndim = 2)
z = np.random.normal(size=(2, n))

# matrix with Ndim rows (here Ndim = 2):
# [[mu1, mu1, ...], [mu2, mu2, ...]]
mean = np.repeat(mu, n).reshape(2, n)

# matrix of random vectors
# vector i: (rand[1][i], rand[2][i])
rand = mean + np.dot(A, z)
```



Weighting method

Sometimes it is not practical to generate random numbers from a distribution $f(x)$

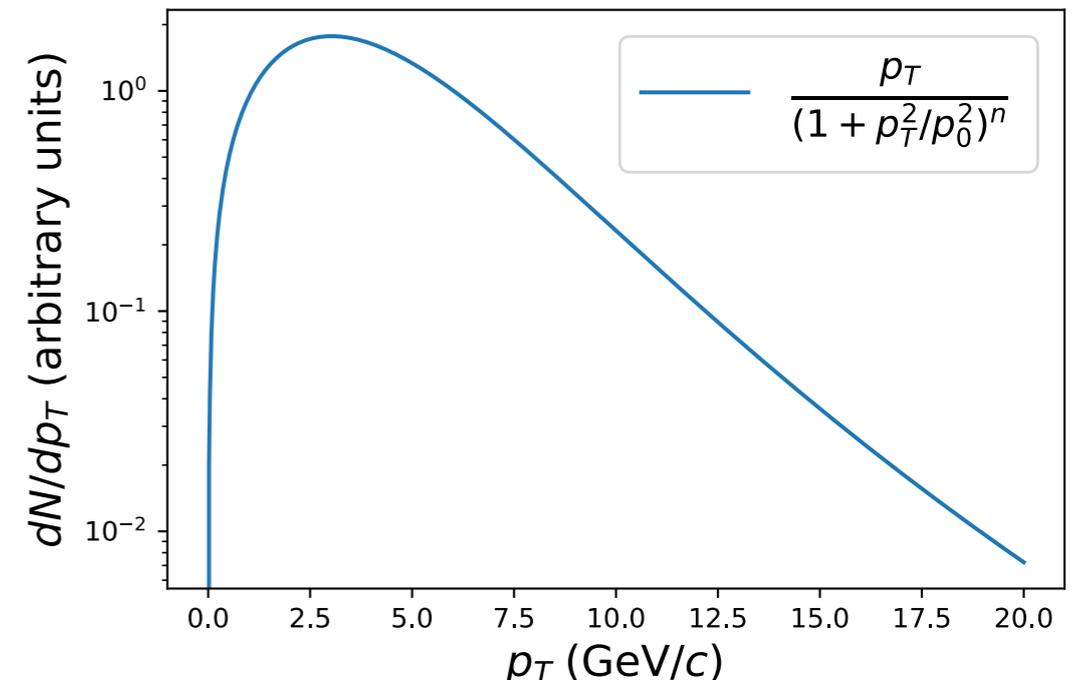
- ▶ for instance, because in the range of interest it varies by several orders of magnitude
- ▶ take p_T spectra as an example: would take long to get sufficient statistics at high p_T

In this case the weighting method may be useful:

1. Generate uniformly distributed random numbers x_i in interval of interest $[x_{\min}, x_{\max}]$
2. Assign a weight $w_i = f(x_i)$ to event i
3. Fill histogram, e.g. for those events that pass certain cuts, with weight w_i , i.e., histogram counter is incremented by w_i , not by 1

More general: define a distribution $h(x)$ which is easy to sample but not necessarily uniform, draw x_i from h , and set $w_i = f(x_i)/h(x_i)$.

Typical p_T spectrum, e.g., of a J/ψ meson



Monte Carlo Integration

Naïve Monte Carlo integration:

$$\underbrace{\int_a^b f(x) dx}_{=: I} = (b-a) \int_a^b f(x) \underbrace{u(x)}_{\substack{\text{uniform distribution} \\ \text{in } [a, b]}} dx = (b-a) \langle f(x) \rangle \approx (b-a) \cdot \underbrace{\frac{1}{n} \sum_{i=1}^n f(x_i)}_{=: \hat{I}}$$

x_i : uniformly distributed random numbers

Typical deviation from the true value of the integral (standard deviation)

$$V[\hat{I}] = \frac{(b-a)^2}{n^2} V\left[\sum_{i=1}^n f(x_i)\right] = \frac{(b-a)^2}{n^2} \cdot n \cdot \sigma^2[f] \quad \rightarrow \quad \sigma[\hat{I}] = \frac{b-a}{\sqrt{n}} \sigma[f]$$

Monte Carlo Integration: Multidimensional integrals

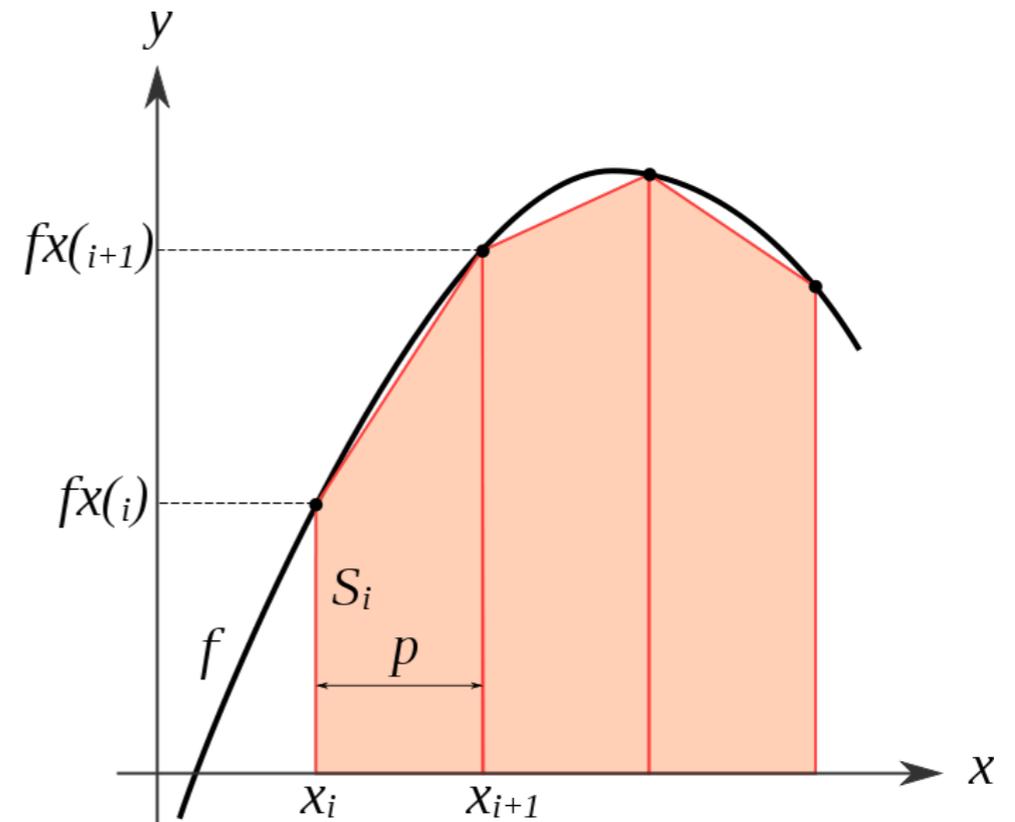
Trapezoidal rule in one dimension

- ▶ accuracy improves as $1/n^2$ with the number of points
- ▶ Much better than $1/\sqrt{n}$ scaling of the MC methods

Monte Carlo integration in d dimensions:

$$I = \int_{\Omega} f(\vec{x}) d\vec{x}, \quad \Omega \subset \mathbb{R}^d, \quad V = \int_{\Omega} d\vec{x}$$

$$I \approx \hat{I} = V \frac{1}{n} \sum_{i=1}^n f(\vec{x}_i), \quad \sigma[\hat{I}] \approx V \frac{\sigma[f]}{\sqrt{n}}$$



https://en.wikipedia.org/wiki/Trapezoidal_rule

← same as in 1d case

Trapezoidal rule in d dimension:

- ▶ accuracy improves as $1/n^{2/d}$ with the number of points
- ▶ for $d > 4$ the dependence on n is better for MC integration

For multidimensional integrals MC integration outperforms other numerical integration methods

Metropolis-Hastings algorithm (1)

Bayesian inference often involves marginalization of a high-dimensional posterior distribution:

$$P(\theta_0|\text{data}) = \int P(\theta_0, \theta_1, \dots, \theta_n|\text{data}) d\theta_1 \dots d\theta_n$$

Typically, the integral cannot be solved in closed form. Moreover, repeated one-dimensional integration becomes inefficient (“curse of dimensionality”).

Idea: sample distribution many times and consider only parameter of interest.

Method: Markov Chain Monte Carlo (MCMC)

MCMC has revolutionized Bayesian analysis.

A sequence of random numbers is a Markov chain if the probability of the next number only depends on the previous one:

$$f(x_{n+1}|x_n, x_{n-1}, \dots, x_0) = f(x_{n+1}|x_n)$$

Metropolis-Hastings algorithm (2)

Goal: sample from a distribution $f(\vec{x})$ known up to a normalization constant.

Take initial \vec{x}_0 with $f(\vec{x}_0) > 0$ and repeat the following steps many times:

1. Generate candidate \vec{y} according to proposal distribution $q(\vec{y} | \vec{x}_k)$
2. Generate uniformly distributed random number r in $[0, 1]$ and set

$$\vec{x}_{k+1} = \begin{cases} \vec{y}, & \text{if } r \leq \alpha(\vec{x}_k, \vec{y}) \\ \vec{x}_k, & \text{otherwise} \end{cases}$$

where

$$\alpha(\vec{x}, \vec{y}) = \min \left\{ 1, \frac{f(\vec{y}) q(\vec{x} | \vec{y})}{f(\vec{x}) q(\vec{y} | \vec{x})} \right\}$$

$\alpha(\vec{x}, \vec{y})$ is called the acceptance probability.

Metropolis-Hastings algorithm (3)

- The algorithm generates a *correlated* sequence of points (not suited for many applications, but okay for marginalization)
- If a finite initial sequence of points is discarded, the remaining points can be shown to follow $f(\vec{x})$
- Not easy to figure out when the sequence has started to converge to $f(\vec{x})$
- The proposal function $q(\vec{y} | \vec{x})$ can be almost anything. Often, a multi-dimensional Gaussian is used.
- Often the proposal function is symmetric, i.e., $q(\vec{y} | \vec{x}) = q(\vec{x} | \vec{y})$. Then the acceptance probability reduces to

$$\alpha(\vec{x}, \vec{y}) = \min \left\{ 1, \frac{f(\vec{y})}{f(\vec{x})} \right\}$$

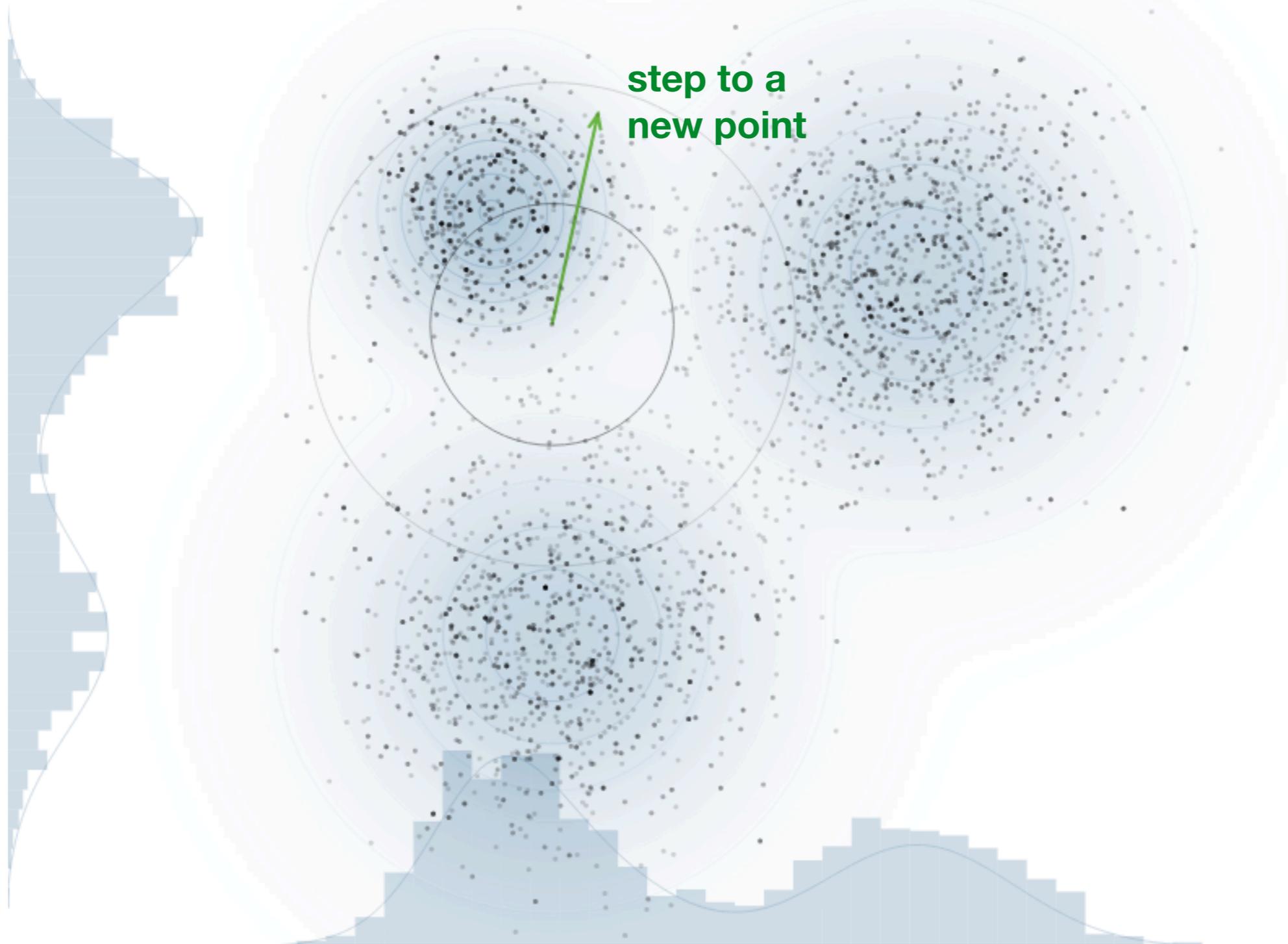
and a step to a higher $f(\vec{y})$ is always taken.

- Original Metropolis algorithm suggested symmetric proposal functions, Hastings modified original rules by using non-symmetric functions.

Metropolis-Hastings algorithm: Visualization

Random walk Metropolis-Hastings

Open Controls

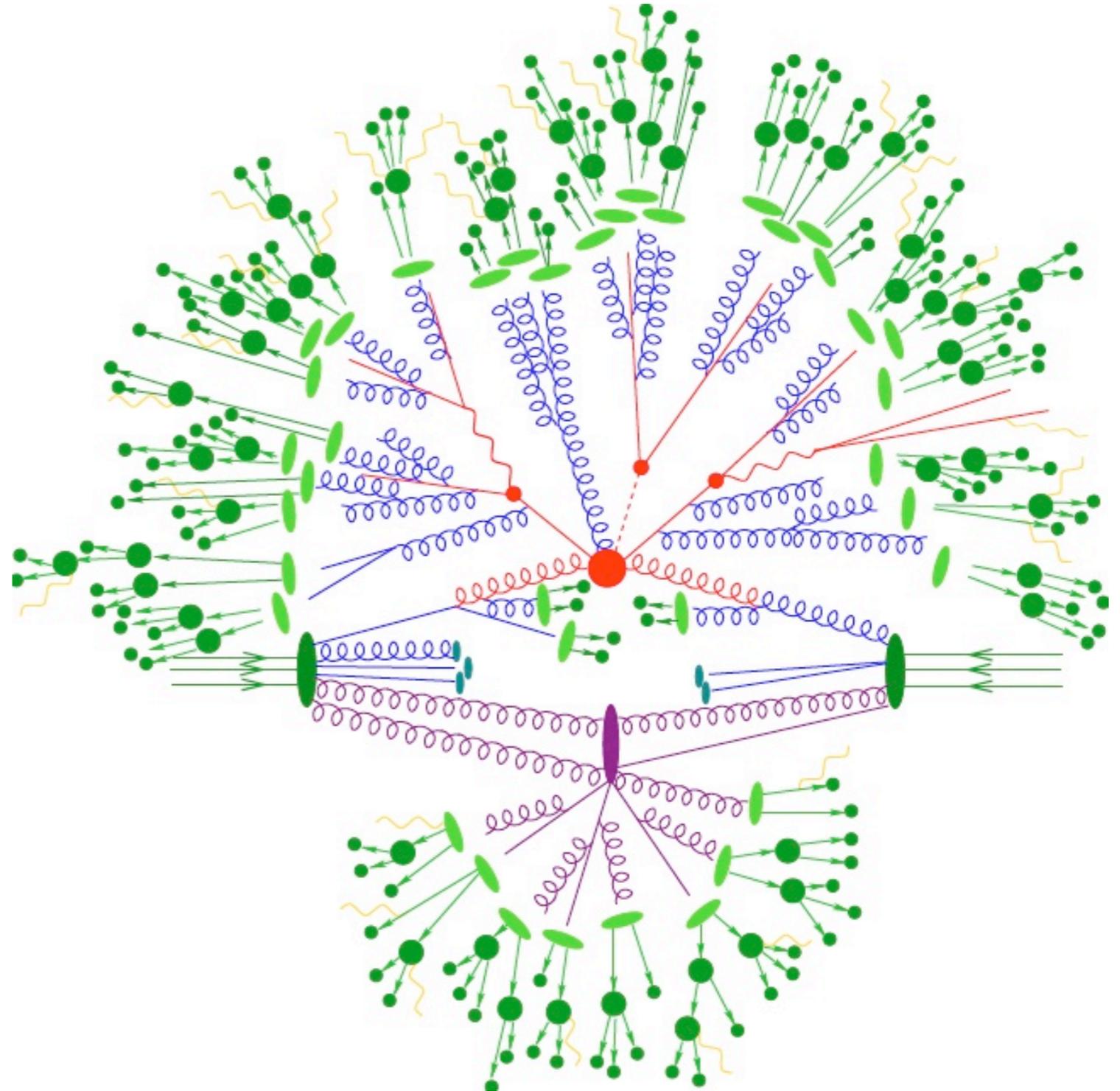


<https://chi-feng.github.io/mcmc-demo>

Monte Carlo simulation I: Event generators (Pythia, Sherpa, ...)

Examples: Pythia

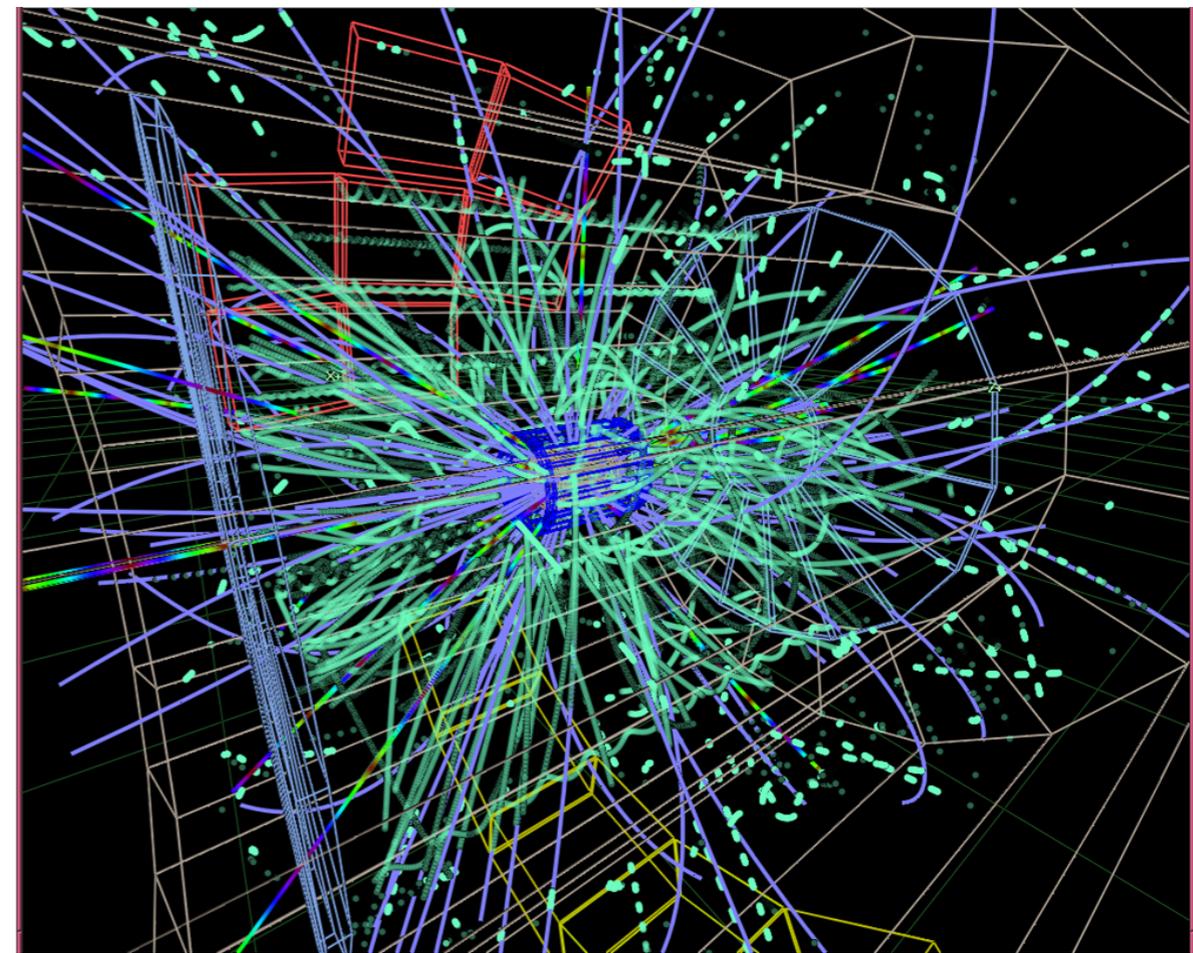
- ▶ Simulation of pp and e^+e^- collision on quark and gluon level
- ▶ Hard and soft interactions, parton showers, fragmentation and particle decay
- ▶ Many applications
 - Test underlying physics, e.g., perturbative QCD
 - Calculate QCD background processes, e.g., in Higgs searches
 - Calculation of detector efficiencies



Pythia

Output:

Four-vectors of produced particles



Event listing (summary)

I	particle/jet	KS	KF	orig	p_x	p_y	p_z	E	m	
1	(u)	A	12	2	0	0.000	0.000	10.000	10.000	0.006
2	(ubar)	V	11	-2	0	0.000	0.000	-10.000	10.000	0.006
3	(string)		11	92	1	0.000	0.000	0.000	20.000	20.000
4	(rho+)		11	213	3	0.098	-0.154	2.710	2.856	0.885
5	(rho-)		11	-213	3	-0.227	0.145	6.538	6.590	0.781
6	pi+		1	211	3	0.125	-0.266	0.097	0.339	0.140
7	(Sigma0)		11	3212	3	-0.254	0.034	-1.397	1.855	1.193
8	(K*+)		11	323	3	-0.124	0.709	-2.753	2.968	0.846
9	p ⁻		1	-2212	3	0.395	-0.614	-3.806	3.988	0.938
10	pi-		1	-211	3	-0.013	0.146	-1.389	1.403	0.140
11	pi+		1	211	4	0.109	-0.456	2.164	2.218	0.140

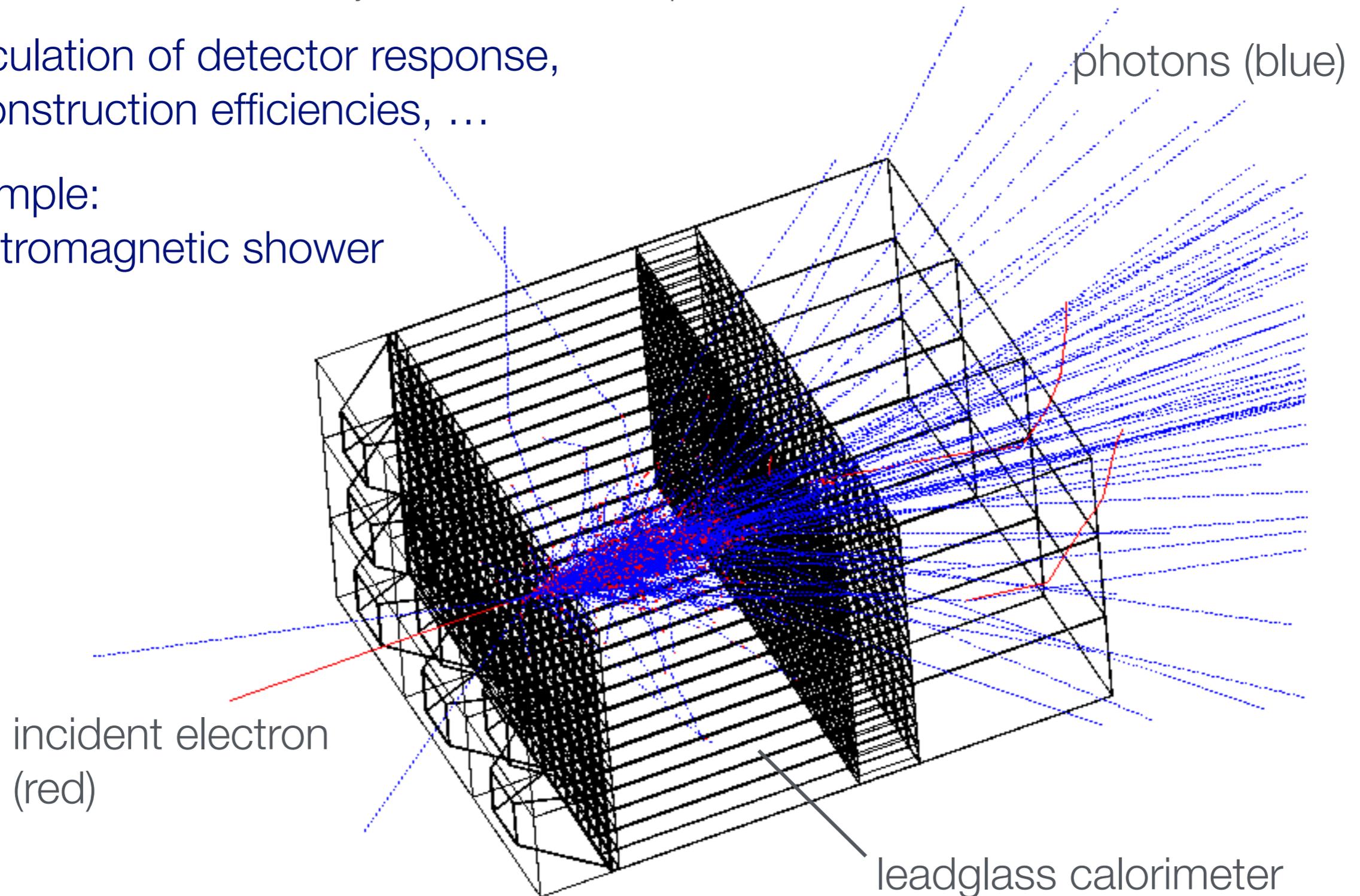
Monte Carlo simulation II: Detector simulation with GEANT

<http://geant4.cern.ch/>

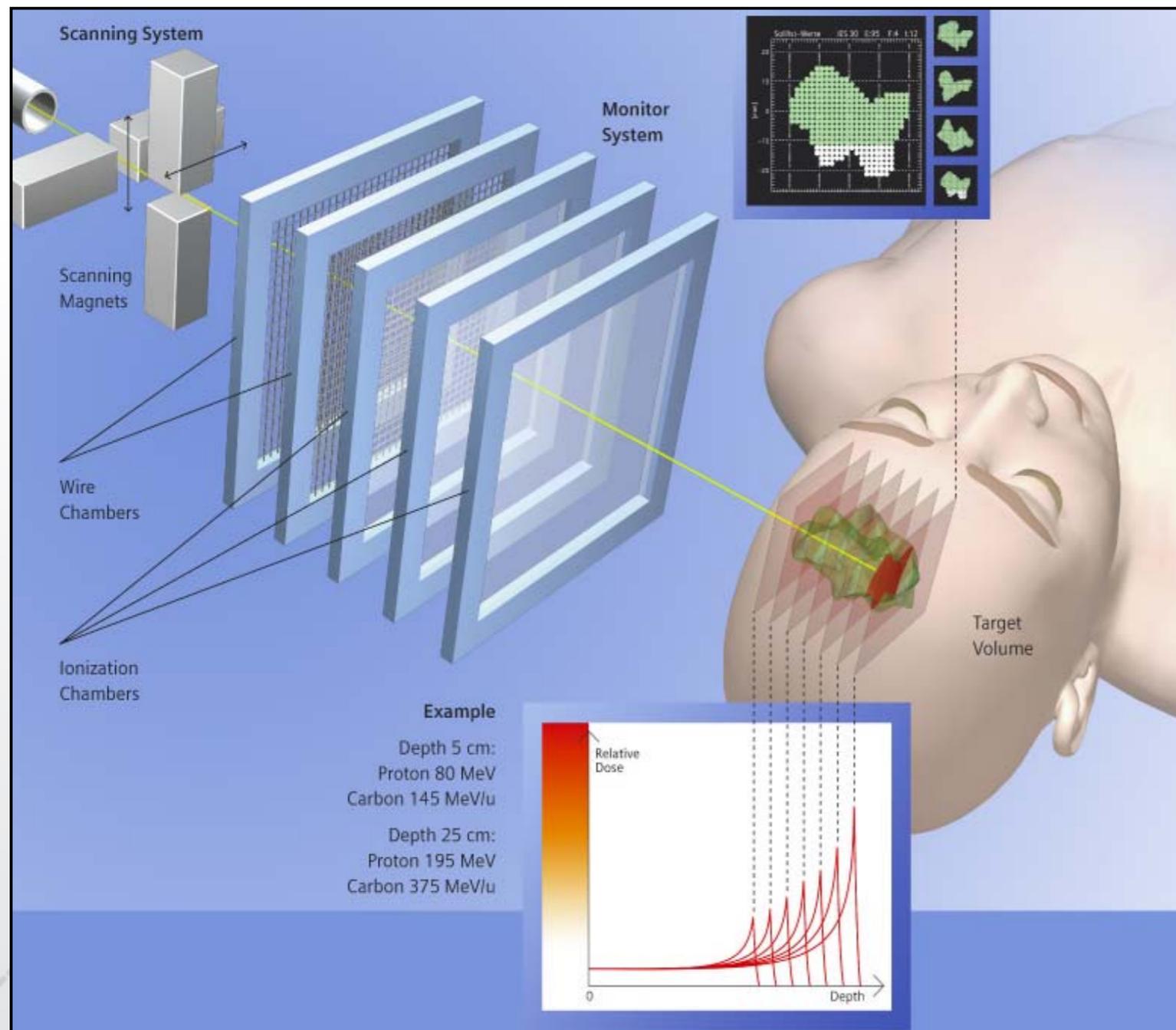
<http://www.uni-muenster.de/Physik.KP/santo/thesis/diplom/kees>

Calculation of detector response,
reconstruction efficiencies, ...

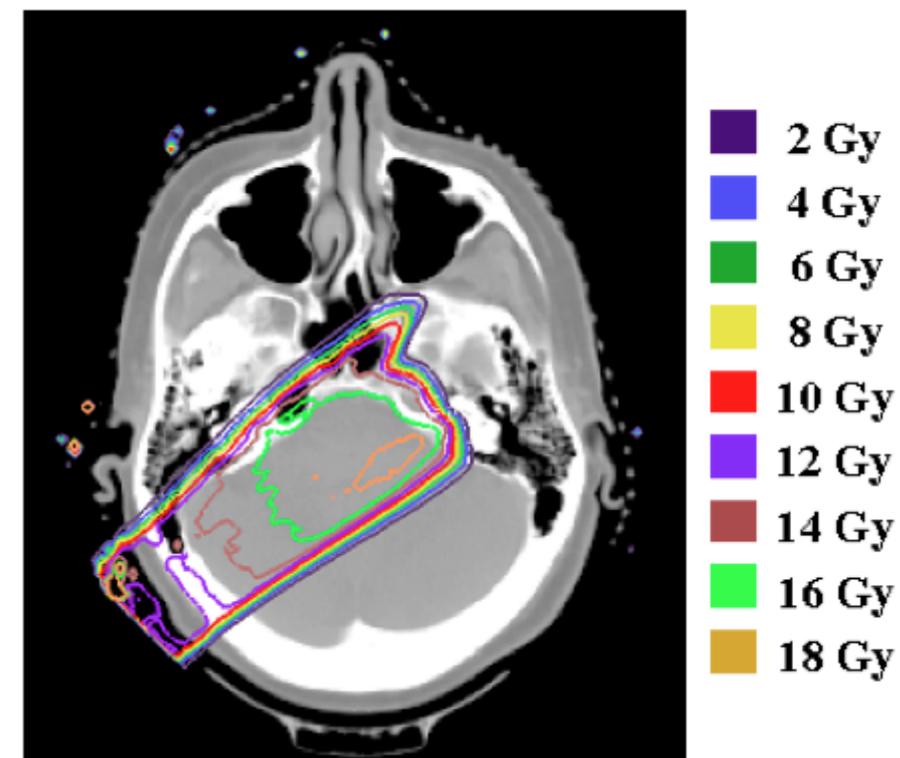
Example:
electromagnetic shower



Monte Carlo simulation III: Treatment planning in radiation therapy



Intensity-Controlled Rasterscan Technique, Haberer et al., GSI, NIM A, 1993



Codes

- ▶ GEANT 4
- ▶ FLUKA
- ▶ ...

Source: GSI