Statistical Methods in Particle Physics

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- Short reminders
- Error propagation
- Correlation between variables

- Monte Carlo methods
 - Transformation method
 - Integration
- Monte Carlo for particle / nuclear physics
 - Event generators
 - Detector simulation

Quick reminders



$$\mathsf{E}[\mathsf{x}] = \int \mathsf{x} \mathsf{f}(\mathsf{x}) \mathsf{d}\mathsf{x} = \mu$$

• Variance:

$$V[x] = E[(x-E[x])^2] = E[x^2]-\mu^2 = \sigma^2$$

• Standard deviation:

$$\sigma = \sqrt{\sigma^2}$$

• Covariance $cov[x,y] = E[(x - \mu_x)(y - \mu_y)]$

Correlation coefficient

 $\rho_{xy} = \frac{\operatorname{cov}[x, y]}{\sigma_{x} \sigma_{y}},$

 $-1 \leq \rho_{xy} \leq +1$





The **accuracy** of a measurement system is the degree of closeness of measurements of a quantity to its true (actual) value.

The **precision** of a measurement system, also called reproducibility or repeatability, is the degree to which repeated measurements under unchanged conditions show the same results.





A measurement system can be accurate but not precise, precise but not accurate. See the grouping of arrows on a target:





high accuracy low precision

low accuracy high precision

Fig 3: A target analogy for the comparison of accuracy and precision. Arrows that strike closer to the bullseye are considered more accurate. if a large number of arrows are shot, precision would be the size of the arrow cluster.

Error propagation

Function of ONE variable:

- Variable x, with mean \bar{x} , and uncertainty σ_x
- Function y = f(x)
 We want to determine the uncertainty on y
- Use the Taylor expansion:

$$f(x) = f(\overline{x}) + (x - \overline{x}) (\frac{df}{dx})_{\overline{x}} + higher order terms$$

We ignore the higher order terms WHEN the measured values are close to the average values and/or the derivative is constant in the region of interest (see in 3 slides)

Not always the case !!!!



Error propagation: one variable

- It follows that: $f(x) f(\overline{x}) = y \overline{y} \approx (x \overline{x}) (\frac{df}{dx})_{\overline{y}}$
 - Variance: $V[y] = \langle (y - \bar{y})^2 \rangle = \langle (x - \bar{x})^2 \rangle (\frac{df}{dx})_{\bar{x}}^2$ $\sigma_y^2 = (\frac{df}{dx})_{\bar{x}}^2 \sigma_x^2$
- Standard deviation

$$\sigma_{y} = \left(\frac{df}{dx}\right)_{\bar{x}} \sigma_{x}$$



Error propagation: one variable



★ How does a "small" change in x, i.e. σ_x , propagate to a small change in y, σ_y

$$\frac{\sigma_y}{\sigma_x} \approx \left(\frac{\mathrm{d}y}{\mathrm{d}x}\right)_{\overline{x}}$$

Ignoring higher order terms



- Neglected second order terms in the Taylor expansion
- This is equivalent to saying that the derivative is constant in region of interest
- This may not always be true...







- ★ Measurement of transverse momentum of a track from a fit
 - radius of curvature of track helix, R, given by

$$R = 0.3B(T)p_T(GeV)$$

- track fit returns a Gaussian uncertainty in radius of curvature, and hence, the PDF is Gaussian in $1/p_{\rm T}$

$$\sigma_{1/p_{\mathrm{T}}}$$

what is the error in *p*_T





★ Measurement of transverse momentum of a track from a fit

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 $\sigma_{1/p_{\mathrm{T}}}$

• what is the error in
$$p_{\rm T}$$

$$\begin{aligned} & |\mathbf{t} \quad x = 1/p_{\mathrm{T}} \\ & p_{\mathrm{T}} = 1/x \\ & \frac{\mathrm{d}p_{\mathrm{T}}}{\mathrm{d}x} = -\frac{1}{x^2} = -p_{\mathrm{T}}^2 \\ & \sigma_{p_{\mathrm{T}}}^2 \quad = \quad \left(\frac{\mathrm{d}p_{\mathrm{T}}}{\mathrm{d}x}\right)^2 \sigma_x^2 \\ & \sigma_{p_{\mathrm{T}}}^2 \quad = \quad \left(p_{\mathrm{T}}^2\right)^2 \sigma_x^2 \\ & \sigma_{p_{\mathrm{T}}} \quad = \quad p_{\mathrm{T}}^2 \sigma_{1/p_{\mathrm{T}}} \end{aligned}$$

Error propagation: two variables



$$a = f(x, y)$$

$$\begin{aligned} \mathbf{a} \ &= \ \mathbf{f}(\mathbf{x}, \mathbf{y}) \ &= \ \mathbf{f}(\bar{\mathbf{x}}, \bar{\mathbf{y}}) \ + \ \frac{d\mathbf{f}}{d\mathbf{x}}(\mathbf{x} \ - \ \bar{\mathbf{x}}) \ + \ \frac{d\mathbf{f}}{d\mathbf{y}}(\mathbf{y} \ - \ \bar{\mathbf{y}}) \ + \ \dots \\ & \sigma_{a}^{2} \ &= \ (\mathbf{a} - \bar{\mathbf{a}})^{2} \ = \ (\mathbf{f}(\mathbf{x}, \mathbf{y}) \ - \ \mathbf{f}(\bar{\mathbf{x}}, \bar{\mathbf{y}}))^{2} \ = \\ & \approx \ \left(\frac{d\mathbf{f}}{d\mathbf{x}}\right)^{2} \left(\mathbf{x} - \bar{\mathbf{x}}\right)^{2} \ + \ \left(\frac{d\mathbf{f}}{d\mathbf{y}}\right)^{2} \left(\mathbf{y} - \bar{\mathbf{y}}\right)^{2} \ + \ 2\frac{d\mathbf{f}}{d\mathbf{x}}\frac{d\mathbf{f}}{d\mathbf{y}}(\mathbf{x} - \bar{\mathbf{x}})(\mathbf{y} - \bar{\mathbf{y}}) \\ & \sigma_{a}^{2} \ = \ \left\langle(\mathbf{a} - \bar{\mathbf{a}})^{2}\right\rangle \ = \\ & \left(\frac{d\mathbf{f}}{d\mathbf{x}}\right)^{2} \left\langle(\mathbf{x} - \bar{\mathbf{x}})^{2}\right\rangle \ + \ \left(\frac{d\mathbf{f}}{d\mathbf{y}}\right)^{2} \left\langle(\mathbf{y} - \bar{\mathbf{y}})^{2}\right\rangle \ + \ 2\frac{d\mathbf{f}}{d\mathbf{x}}\frac{d\mathbf{f}}{d\mathbf{y}} \left\langle(\mathbf{x} - \bar{\mathbf{x}})(\mathbf{y} - \bar{\mathbf{y}})\right\rangle \ = \end{aligned}$$

Error propagation: two variables



$$\sigma_{a}^{2} = \left(\frac{df}{dx}\right)^{2} \sigma_{x}^{2} + \left(\frac{df}{dy}\right)^{2} \sigma_{y}^{2} + 2\frac{df}{dx}\frac{df}{dy}\left(\frac{cov[x,y]}{\sigma_{x}\sigma_{y}}\right)\sigma_{x}\sigma_{y}$$
$$\frac{cov[x,y]}{\sigma_{x}\sigma_{y}} = \rho = \text{correlation coefficient}$$

- $-1 \le \rho \le +1$
- ρ = 0 : variables are INDEPENDENT
- $\rho \neq 0$: variables are CORRELATED
 - *ρ* > 0 : correlated
 - $\rho < 0$: anti-correlated

Independent variables



$$\sigma_{\rm f}^2 = \left(\frac{{\rm df}}{{\rm dx}}\right)^2 \sigma_{\rm x}^2 + \left(\frac{{\rm df}}{{\rm dy}}\right)^2 \sigma_{\rm y}^2$$

Important examples:

Function	Derivative(s)	Variance	Standard deviation
$f = kx$; $k \in \mathbb{R}$	$\frac{\partial f}{\partial x} = k$	$\sigma_f^2 = k^2 \sigma_x^2$	$\sigma_f = k\sigma_x$
f = x + y	$\frac{\partial f}{\partial x} = 1$ and $\frac{\partial f}{\partial y} = 1$	$\sigma_f^2 = \sigma_x^2 + \sigma_y^2$	$\sigma_f = \sqrt{\sigma_x^2 + \sigma_y^2}$
f = x - y	$\frac{\partial f}{\partial x} = 1$ and $\frac{\partial f}{\partial y} = -1$	$\sigma_f^2 = \sigma_x^2 + \sigma_y^2$	$\sigma_f = \sqrt{\sigma_x^2 + \sigma_y^2}$
f = x y	$\frac{\partial f}{\partial x} = y$ and $\frac{\partial f}{\partial y} = x$	$\left(\frac{\sigma_f}{f}\right)^2 = \left(\frac{\sigma_x}{x}\right)^2 + \left(\frac{\sigma_y}{y}\right)^2$	$\sigma_f = f \sqrt{\left(\frac{\sigma_x}{x}\right)^2 + \left(\frac{\sigma_y}{y}\right)^2}$
f=x/y	$\frac{\partial f}{\partial x} = \frac{1}{y}$ and $\frac{\partial f}{\partial y} = -\frac{x}{y^2}$	$\left(\frac{\sigma_f}{f}\right)^2 = \left(\frac{\sigma_x}{x}\right)^2 + \left(\frac{\sigma_y}{y}\right)^2$	$\sigma_f = f \sqrt{\left(\frac{\sigma_x}{x}\right)^2 + \left(\frac{\sigma_y}{y}\right)^2}$

Error propagation: SPECIAL CASES



$$y = x_1 + x_2 \rightarrow \sigma_y^2 = \sigma_1^2 + \sigma_2^2 + 2cov[x_1, x_2]$$

$$y = x_1 x_2 \rightarrow \frac{\sigma_y^2}{y^2} = \frac{\sigma_1^2}{x_1^2} + \frac{\sigma_2^2}{x_2^2} + 2\frac{\text{cov}[x_1, x_2]}{x_1 x_2}$$

That is, **if the x**, **are uncorrelated**:

Add errors quadratically for the sum (or difference), Add relative errors quadratically for product (or ratio)



correlations can change this completely...



Consider $y = x_1 - x_2$ with:

$$\mu_1 = \mu_2 = 10, \quad \sigma_1 = \sigma_2 = 1, \quad \rho = \frac{\text{cov}[x_1, x_2]}{\sigma_1 \sigma_2} = 0$$

 $V[y] = 1^2 + 1^2 = 2 \quad \rightarrow \quad \sigma_y = 1.4$

Now suppose $\rho=1$ (full correlation). Then:

$$V[y] = \gamma^2 + \gamma^{\prime} - \gamma = \cdot \quad \rightarrow \quad \sigma_y = 0$$

i.e. for 100% correlation, the error in the difference goes to 0 !!





We wish to calculate the average speed (displacement/time) of an object. Assume is displacement is measured as $x = 22.2 \pm 0.5$ cm during the time interval t = 9.0 ± 0.1 s.

Calculate speed and error on the speed.





We wish to calculate the average speed (displacement/time) of an object. Assume is displacement is measured as $x = 22.2 \pm 0.5$ cm during the time interval t = 9.0 ± 0.1 s.

Calculate speed and error on the speed.

$$v = \frac{x}{t} = \frac{22.2}{9.0} = 2.467 \text{ cm/s}$$
$$\sigma_v = v \sqrt{\left(\frac{\sigma_x}{x}\right)^2 + \left(\frac{\sigma_t}{t}\right)^2} = 2.467 \sqrt{\left(\frac{0.5}{22.2}\right)^2 + \left(\frac{0.1}{9.0}\right)^2} = 0.062 \text{ cm/s}$$

We report the result as: 2.467 ± 0.062 cm/s.



Important case: combine the results of independent experiments

Consider we have n independent experiments with results ai and errors σ_i (i = 1, ..., n). We can combine the results from each experiment to form a more accurate result. For this, a weighted sum is performed where experiments with smaller errors contribute more to the combined result.

The statistically correct way to combine independent results is:

$$a = \frac{\sum a_i / \sigma_i^2}{\sum 1 / \sigma_i^2}$$
 and $\sigma = \frac{1}{\sqrt{\sum 1 / \sigma_i^2}}$





- For the measured gravitational acceleration data: 9.77±0.14, 9.82±0.10 and 9.86±0.20 m/s² the combined result is:
- Example: Power in an electric circuit. $P = I^2 R$
 - Let $I = 1.0 \pm 0.1$ amp and $R = 10 \pm 1 \Omega$
 - $rac{P}{r} = 10$ watts
 - calculate the variance in the power using propagation of errors



12"



- For the measured gravitational acceleration data: 9.77±0.14, 9.82±0.10 and 9.86±0.20 m/s² the combined result is: 9.811 ± 0.075 m/s²
- Example: Power in an electric circuit. $P = I^2 R$
 - Let I = 1.0 ± 0.1 amp and R = 10 ± 1 Ω

 P = 10 watts
 - calculate the variance in the power using propagation of errors

$$\sigma_P^2 = \sigma_I^2 \left(\frac{\partial P}{\partial I}\right)_{I=1}^2 + \sigma_R^2 \left(\frac{\partial P}{\partial R}\right)_{R=10}^2 = \sigma_I^2 (2IR)^2 + \sigma_R^2 (I^2)^2 = (0.1)^2 (2 \cdot 1 \cdot 10)^2 + (1)^2 (1^2)^2 = 5 \text{ watts}^2$$

$$P = 10 \pm 2 \text{ watts}$$

 \overline{x}

х

 $\langle \operatorname{cov}(x, y) \rangle < 0$

If x and y are anti-correlated

Correlated variables

The covariance matrix and the correlation coefficient express to what extent 2 or more variables "co-vary" randomly, or whether, when one has a given variation, the second one varies by a corresponding quantity / way of behaviour.

 $\langle \operatorname{cov}(x,y) \rangle = 0 \quad \overline{y}$

 \overline{v}

x and y are uncorrelated, i.e. INDEPENDENT



More correlation





Figure 2: Examples of correlations and anticorrelations



Consider pairs of jets in one event:

From the total energy of each jet, the di-jet invariant mass can be calculated

$$m^2 = E_1 E_2 (1 - \cos \theta)$$





 E_2

 E_1

this type of correlation can be handled mathematically

Origin of correlation







Suppose we measure a set of values $\vec{x} = (x_1, ..., x_n)$

which follow some joint pdf $f(\vec{x})$.

 $f(\vec{x})$ might be not fully known. But we have the covariances:

 $V_{ij} = cov[x_i, x_j]$, and the means $\vec{\mu} = E[\vec{x}]$ (in practice only estimates)

Now consider a function $y(\vec{x})$.

What is the variance of $y(\vec{x})$?

Hard way: use joint pdf $f(\vec{x})$ to find the pdf g(y),

Then from g(y) find

$$V[y] = E[y^2] - (E[y])^2$$

Often NOT practical. $f(\vec{x})$ may not even be fully known ...



Expand $y(\vec{x})$ to the first order in a Taylor series about $\vec{\mu}$

$$\mathbf{y}(\mathbf{\vec{x}}) \approx \mathbf{y}(\mathbf{\vec{\mu}}) + \sum_{i=1}^{n} \left[\frac{\partial \mathbf{y}}{\partial \mathbf{x}_{i}}\right]_{\mathbf{\vec{x}}=\mathbf{\vec{\mu}}} (\mathbf{x}_{i}-\mathbf{\mu}_{i})$$

To find the variance V[y] we need $E[y^2]$ and E[y]:

$$E[y(\vec{x})] \approx y(\vec{\mu})$$
 since $E[x_i - \mu_i] = 0$

Error propagation - 3



$$E[y^{2}(\vec{x})] \approx y^{2}(\vec{\mu}) + 2y(\vec{\mu}) \sum_{i=1}^{n} \left[\frac{\partial y}{\partial x_{i}}\right] E[x_{i} - \mu_{i}]$$

$$+ E\left[\left(\sum_{i=1}^{n} \left[\frac{\partial y}{\partial x_{i}}\right]_{\vec{x}=\vec{\mu}} (x_{i} - \mu_{i})\right) \left(\sum_{j=1}^{n} \left[\frac{\partial y}{\partial x_{j}}\right]_{\vec{x}=\vec{\mu}} (x_{j} - \mu_{j})\right)\right]$$

$$= y^{2}(\vec{\mu}) + \sum_{i,j=1}^{n} \left[\frac{\partial y}{\partial x_{i}} \frac{\partial y}{\partial x_{j}}\right] V_{ij}$$

Putting the ingredients together gives the variance of $y(\vec{x})$

$$\sigma_{y}^{2} \approx \sum_{i,j=1}^{n} \left[\frac{\partial y}{\partial x_{i}}\frac{\partial y}{\partial x_{j}}\right]_{\vec{x}=\vec{\mu}} V_{ij}$$



If the x_i are uncorrelated, i.e. $V_{ij} = \sigma_i^2 \delta_{ij}$, then this becomes:

$$\sigma_{y}^{2} \approx \sum_{i=1}^{n} \left[\frac{\partial y}{\partial x_{i}}\right]^{2}_{\vec{x}=\vec{\mu}} \sigma_{i}^{2}$$

Similar for a set of m functions $\vec{y}(\vec{x}) = (y_1(\vec{x}), ..., y_m(\vec{x}))$

$$U_{kl} = cov[y_k, y_l] \approx \sum_{i,j=1}^{n} \left[\frac{\partial y_k}{\partial x_i} \frac{\partial y_l}{\partial x_j}\right]_{\vec{x}=\vec{\mu}} V_{ij}$$

Or in matrix notation $U = A V A^T$, where $A_{ij} = \left[\frac{\partial Y_i}{\partial X_j}\right]_{\vec{x} = \vec{\mu}}$



Monte Carlo methods are a class of computational algorithms that rely on repeated random sampling to compute their results.

Monte Carlo methods are often used in computer simulations of physical and mathematical systems.

These methods are most suited to calculation by a computer and tend to be used when it is unfeasible to compute an exact result with a deterministic algorithm

The name

The Monte Carlo method was coined in the **1940s** by John von Neumann, Stanislaw Ulam and Nicholas Metropolis, while they were working on **nuclear weapon projects** (Manhattan Project) in the Los Alamos National Laboratory. It was named in homage to the **Monte Carlo Casino**, a famous casino, where Ulam's uncle would often gamble away his money

Random processes were used extensively for the first time to predict theoretically the interaction of neutrons with matter









An early variant of the Monte Carlo method can be seen in the

Buffon's needle experiment (18th century)

in which π can be estimated by dropping needles on a floor made of parallel strips of wood.



In more mathematical terms:

Given a needle of length I dropped on a plane ruled with parallel lines t units apart, what is the probability that the needle will cross a line?

If I ≤ t then: P =
$$\frac{2I}{t\pi}$$

Use this to estimate π !





- In the 1930s, Enrico Fermi first experimented with the Monte Carlo method while studying neutron diffusion, but did not publish anything on it
- In 1946, physicists at Los Alamos Scientific Laboratory were investigating radiation shielding and the distance that neutrons would likely travel through various materials. Despite having most of the necessary data, such as the average distance a neutron would travel in a substance before it collided with an atomic nucleus or how much energy the neutron was likely to give off following a collision, the problem could not be solved with analytical calculations. Stanisław Ulam had the idea of using random experiments.

D

A bit subjective. Sawilowsky:

a simulation is a fictitious representation of reality, a Monte Carlo method is a technique that can be used to solve a mathematical or statistical problem, and a Monte Carlo simulation uses repeated sampling to determine the properties of some phenomenon (or behavior). Examples:

- Simulation: Drawing one pseudo-random uniform variable from the interval [0,1] can be used to simulate the tossing of a coin: If the value is less than or equal to 0.50 designate the outcome as heads, but if the value is greater than 0.50 designate the outcome as tails. This is a simulation, but not a Monte Carlo simulation.
- Monte Carlo method: The area of an irregular figure inscribed in a unit square can be determined by throwing darts at the square and computing the ratio of hits within the irregular figure to the total number of darts thrown. This is a Monte Carlo method of determining area, but not a simulation.
- Monte Carlo simulation: Drawing a large number of pseudo-random uniform variables from the interval [0,1], and assigning values less than or equal to 0.50 as heads and greater than 0.50 as tails, is a Monte Carlo simulation of the behavior of repeatedly tossing a coin.

Not always so easy to distinguish

The Monte Carlo method

A numerical technique for calculating probabilities and related quantities using sequences of random numbers

The usual steps:

- Generate sequence r₁, r₂, ..., r_m uniform in [0,1]
- Use this to produce another sequence x₁, x₂, ..., x_m distributed according to some pdf f(x) in which we are interested (x can be a vector)

Applications:

- MC calculation for integration
- Simulation to test statistical procedures





Statistical Methods, Lecture 4, November 5, 2012



Random numbers





Transformation method

- Random variable x
- Pdf f(x)
- cumulative distribution function

$$F(x) = \int_{-\infty}^{x} f(t)dt$$

Case of F(x) analitically invertible:

 $x = F^{-1}(u)$

• If u_i uniform in [0,1], then $x_i = F^{-1}(u_i)$ follow pdf f(x)

Method is applicable if F(x) and $F^{-1}(u)$ are analytically solvable





Consider random numbers according to:

$$f(\mathbf{x}, \lambda) = \begin{cases} \lambda e^{-\lambda \mathbf{x}}, \mathbf{x} > 0\\ 0, \mathbf{x} \le 0 \end{cases}$$

Computation of the inverse pdf:

$$\int_{-\infty}^{\mathbf{x}} \mathbf{f}(t) dt = \int_{0}^{\mathbf{x}} \lambda \, \mathbf{e}^{-\lambda t} \, dt = \left[\mathbf{e}^{-\lambda t} \right]_{0}^{\mathbf{x}} = \mathbf{1} - \mathbf{e}^{-\lambda \mathbf{x}} = \mathbf{r}(\mathbf{x})$$

1000

F

And solve for x(r).

And solve for x(r).

$$\rightarrow x(r) = -1/\lambda \ln(1-r)$$

$$x(r) = -1/\lambda \ln(1-r)$$

250



Hit and miss method (von Neumann)

If $F^{-1}(u)$ is not computable, then use "hit and miss" method (also called acceptance-rejection method) $\mathcal{F}^{0.5}$

Enclose the pdf in a box:

 Generate a random number x, uniform in [x_{min},x_{max}], i.e.

$$x = x_{min} + r_1(x_{max} - x_{min})$$

r_ uniform in [0,1]

- Generate a second indipendent random number uniformly distributed between 0 and fmax, i.e. u=r₂ f_{max}
- If u < f(x), then accept x if not, reject x and repeat





Example



 $f(x) = \frac{3}{8}(1+x^2)$

 $(-1 \leq x \leq 1)$

0 └ -1 -0.5

0

х

0.5

1



The fraction of accepted points is equal to the fraction of the box's area under the curve.

For very peaked distributions, this may be very low and thus the algorithm may be slow.

Improve by enclosing the pdf f(x) in a curve C h(x) that conforms to f(x) more closely, where h(x) is a pdf from which we can generate random values and C is a constant.



Generate points uniformly over C h(x). If point is below f(x), accept x. Check accuracy of the method:







For 1-dimensional integral:

- MC: $n \propto$ number of random values generated accuracy $\propto 1/\sqrt{n}$
- Trapezoid: $n \propto$ number of subdivisions accuracy $\propto 1/n^2$

Trapezoid wins! But in d dimensions this becomes

MC: accuracy $\propto 1/\sqrt{n}$ \leftarrow independent of d ! Trapezoid: accuracy $\propto 1/n^{2/d}$

For high enough d (d>4), MC always wins



Often an analytical treatment of physical problems is either difficult or impossible. Therefore we do either an approximation or use a statistical description (via Monte Carlo)

APPLICATIONS:

- High energy and nuclear physics
- Numerical calculations (integration, differentiation)
- Coding/encoding (e.g. secure connections, like ssh)
- Reliability tests
- Investment banking
- Earth sciences

METHODS:

- Find a statistic model
- Produce random numbers properly
- Calculate estimators from random quantities



Qualitatively:

Scattering experiment:

Measure the angular distribution of particles scattered from protons in a fixed target

Ingredients:

- Magnitude and direction of the momentum vector of the incident particles
- Probability that a particle will collide with a proton in the target
- Resulting momentum vectors of the scattered particles

All are described in terms of probability distributions !

The final experimental result can be treated in terms of a multiple integration over all these probability distributions !!



Several stages:

• Event generator:

- Simulation of the PHYSICS process
- Colliding particles
- Cross section, processes involved, fragmentation ...

Detector simulation:

- Interaction of the produced particles with the material
- Realistic description of the experimental apparatus
 - efficiencies
 - defects (dead channels, etc)
 - misalignment

Event generators



• $e^+e^- \rightarrow hadrons$

- JETSET (PYTHIA)
- HERWIG
- ARIADNE

• $e^+e^- \rightarrow WW$

- KORALW
- EXCALIBUR
- ERATO

• $pp \rightarrow hadrons$

- ISAJET
- PYTHIA
- HERWIG
- **PbPb** \rightarrow hadrons HIJING



The output are so-called "events", namely for each collision the programs give a list of final state particles, with their momentum vectors, types, angular distribution, etc

X-			
Event listing (sunnery)	A simulated event		
I particle/jet KS KF orig p_x p_y p_z E	n		
1 !p+! 21 2212 0 0,000 0,000 7000,000 7000, 2 !p+! 21 2212 0 0,000 0,000 7000,000 7000,	000 0.938		
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	8E2 0,000 415 0,000 397 pi+ 1 211 209 0,006 0,238 -308,296 308,297 0,140 398 genus 1 22 211 0,407 0,067 -1685,469 1695,458 0,000 399 genus 1 22 211 0,417 -0,029 -314,822 314,822 0,000 400 (pi0) 11 111 212 0,021 0,122 -103,709 103,703 0,135 401 (pi0) 11 111 212 0,021 0,122 -103,709 103,703 0,135 402 (pi0) 11 111 212 0,267 -0,052 -144,673 144,674 0,135 402 (pi0) 11 111 212 0,267 -0,052 -144,673 144,674 0,135 403 genus 1 22 215 -1,494 2,143 3,051 4,016 0,000 405 pi^+ 1 -215 -0,024		
18 "chi_101 21 1000022 12 -136,265 -72,201 33,246 181, 19 ru_wul 21 14 12 -78,265 -72,961 33,246 181, 19 ru_wul 21 14 12 -78,263 -24,757 21,719 84, 20 ru_wubarl 21 -14 12 -107,801 16,901 38,225 115,	$\begin{array}{cccccccccccccccccccccccccccccccccccc$		
21 genma 1 22 4 2,635 1,357 0,125 2 22 ("chi_1-) 11-1000024 9 129,643 112,440 129,820 262 23 ("chi_20) 11 1000023 12 -322,330 -80,817 113,191 382 24 "chi_10 1 1000022 15 97,944 77,819 80,917 163 25 "chi_10 1 1000022 18 -136,266 -72,961 53,246 181 26 mmu 1 14 19 -78,263 -24,757 21,719 84 27 mmuber 1 -14 20 -107,801 16,901 38,226 115 28 (Delta++) 11 2224 2 0,222 0,012-2734,287 2734	$\begin{array}{cccccccccccccccccccccccccccccccccccc$		
PYTHIA Monte Carlo	$\begin{array}{cccccccccccccccccccccccccccccccccccc$		
$pp \rightarrow gluino - gluino$			



INPUT: particle list (with their species and momenta) from the event generator

Simulate the detector response taking into account:

- Multiple Coulomb scattering (generate scattering angle)
- Particle decays (generate lifetime), nuclear knock-out
- Ionization energy loss (generate Δ , Landau)
- Bremsstrahlung
- Electromagnetic / hadronic showers









- First version ~ 1974
- Till GEANT 3.21, in FORTRAN
- Since ~ 2000, FORTRAN version no longer developed, bug fixes
- Geant4: in C++, with a modern object-oriented design
- Next ... Geant 5

The detector simulation takes into account many more things:

- Production of the signals (electronics response)
- Addition of detector noise
- Description of the detection efficiency for each detector component (experiment specific)
- Position and energy resolution of each detector component (experiment specific)

The output is a list of digitized signals from all detector components, exactly like real data!! (or data format input for the reconstruction)



Use of simulations

- Develop reconstruction algorithms (particle trajectories in the tracking detectors, showers in the calorimeters)
- Optimize trigger selection
- Identify the best signal signature
- Compute efficiency of selections in real data analysis
- During design of an experiment: define the detector acceptance, etc

Simulation is absolutely crucial in the planning phase of experiments, for preparation of data taking, to optmize analyses, to evaluate the significance of the results



Geant – other applications



Proton beam eye therapy unit at the Laboratori Nazionali del Sud (INFN) in Catania (left) and a display from the Geant4 advanced example for the simulation of the same beam line (right).



Geant4 simulated dose contours in a human brain with a proton beam.



ALICE (TPC) simulation: proton-proton





ALICE (TPC) simulation: Pb-Pb





ALICE simulation: Pb-Pb







ALICE simulation: Pb-Pb





2 degree slice ONLY!!

(~ 500 tracks)

(a bit old ...)