Statistical Methods in Particle Physics

Lecture 3 October 29, 2012

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Statistical Methods, Lecture 3, October 29, 2012

Outline

- Reminder:
 - Probability density function
 - Cumulative distribution function
- Functions of random variables
- Expectation values
- Covariance, correlation

Examples of probability functions:

- Binomial
- Multinomial
- Poisson
- Uniform
- Exponential
- Gaussian
 - Central limit theorem

- Chi-square
- Cauchy
- Landau



Suppose outcome of experiment is **continuous** value x:

$$P(x \text{ found in } [x, x+dx]) = f(x)dx$$

\rightarrow f(x) = probability density function (pdf)

$$\int_{-\infty}^{\infty} f(x) dx = 1$$
 Normalization
(x must be somewhere)

Note:

With:

• f(x) ≥ 0

- -

• f(x) is NOT a probability ! It has dimension 1/x !



Cumulative distribution function (cdf)





- F(x) is a continuously non-decreasing function
- F(-∞)= 0, F(∞)=1
- For well behaved distributions:

pdf:
$$f(x) = \frac{\partial F(x)}{\partial x}$$





The outcome of the experiment is characterized by more than 1 quantity, e.g. by x and y

$$P(A \cap B) = f(x, y) dx dy$$
Joint pdf

 $\iint f(x, y) dx dy = 1$

Normalization:

у event A 8 6 4 event B 2 dx 0 2 6 8 10 4 0

х

$$\iint \dots \int f(x_{1,}x_{2,.} \dots x_{n}) dx_{1} dx_{2.} \dots dx_{n} = 1$$

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Marginal pdf's

From a multivariate distribution f(x,y) dx dy (e.g. scatter plot) we might be in interested only in the pdf of ONE of the components (x or y, here)

→ projection of joint pdf onto individual axes Marginal pdf

$$f_{x}(x) = \int f(x,y)dy$$
$$f_{y}(y) = \int f(x,y)dx$$

Distribution of a single variable which is part of a multivariate distribution



A function of a random variable is itself a random variable.

Suppose x follows a pdf f(x), consider a function a(x). What is the pdf g(a)?

$$g(a)da = \int_{dS} f(x)dx$$

dS = region of x space for which a is in [a, a+da].

For one-variable case with unique inverse this is simply:

$$g(a)da = \left| \int_{x(a)}^{x(a+da)} f(x')dx' \right| = \int_{x(a)}^{x(a)+\left|\frac{dx}{da}\right|da} f(x')dx' \qquad g(a) = f(x(a)) \left|\frac{dx}{da}\right|da$$





Consider a continuous random variable x with pdf f (x). Define **expectation (mean) value** as

$$\mathsf{E}[\mathsf{x}] = \int \mathsf{x}\mathsf{f}(\mathsf{x})\mathsf{d}\mathsf{x}$$

E[x] is NOT a function of x, it is rather a parameter of f(x)

Notation (often):

$$E[x] = \mu$$
 ~ "centre of gravity" of pdf

For a function y(x) with pdf g(y),

$$\mathsf{E}[y] = \int yg(y)dy = \int y(x)f(x)dx \qquad \text{(equivalent)}$$



Variance and standard deviation



Variance: $V[x] = E[(x-E[x])^2] = E[x^2]-\mu^2$

Notation:
$$V[x] = \sigma^2$$

Standard deviation: $\sigma = \sqrt{\sigma^2}$

Same dimension as x







• Find the mean of the random variable X that has probability density function f given by:

 $f(x) = x^2 / 3$ for -1 < x < 2

 Suppose that X has the power distribution with parameter a > 1, which has density:

$$f(x) = (a - 1)x^{-a}$$
 for x > 1

Show that:

$$E[x] = \begin{cases} \infty, \text{if } 1 < a \le 2\\ \frac{a-1}{a-2}, \text{if } a > 2 \end{cases}$$

• Let the random variable x have the probability density function $f(x) = \begin{cases} 3x^{2}, & \text{if } 0 \le x \le 1 \\ 0. & \text{elsewhere} \end{cases}$ Calculate its variance. Define **covariance** cov[x,y] (also use matrix notation V_{xy}) as:

$$cov[x,y] = E[(x - \mu_x)(y - \mu_y)]$$

Can be written as:

$$cov[x,y] = E[xy] - \mu_x \mu_y$$

Correlation coefficient (dimensionless) defined as:

$$\rho_{xy} = \frac{\operatorname{cov}[x, y]}{\sigma_x \sigma_y}, \qquad -1 \le \rho_{xy} \le +1$$



Correlation coefficient





$$\rho = -0.75$$



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If x and y are independent, i.e. $f(x,y) = f_x(x) f_y(y)$, then:

$$\mathsf{E}[\mathsf{x}\mathsf{y}] = \iint \mathsf{x}\mathsf{y}\mathsf{f}(\mathsf{x},\mathsf{y}) \,\mathsf{d}\mathsf{x} \,\mathsf{d}\mathsf{y} = \mu_{\mathsf{x}}\mu_{\mathsf{y}}$$

Therefore: cov[x, y] = 0

x and y are 'uncorrelated'

Note!! The converse is NOT always true!!!





Let [x y] be an absolutely continuous random vector with domain:

$$R_{xy} = \{(x, y): 0 \le x \le y \le 2\}$$

i.e. R_{xy} is the set of all couples (x,y) such that $0 \le y \le 2$ and $0 \le x \le y$. Let the joint probability density function of [x y] be:

$$f(x,y) = \begin{cases} \frac{3}{8}y, if(x,y) \in R_{XY} \\ 0, otherwise \end{cases}$$

Compute the covariance between X and Y.

Coin is tossed in the air \rightarrow 50% heads up, 50% tails up

Meaning: if we continue tossing a coin repeatedly, the fraction of times that it lans heads up will asymptotically approach 1/2. For each given toss, the probability cannot determine whether or not it will land heads up; it can only describe how we should expect a large number of tosses to be divided into two possibilities.



You flipped 2 coins of type US \$1 - George







Suppose we toss two coins at the time

 \rightarrow There are 4 different possible PERMUTATIONS of the way in which they can land:

- Both heads up
- Both tails up
- 2 mixtures of heads and tails depending on which one is heads up

Each permutation is equally probable \rightarrow the probability for any choice of them is 25% !

For the probability for the mixture of heads and tails, without differentiating between the two kinds of mixtures, we add two cases $\rightarrow 50\%$

THE SUM OF THE PROBABILITIES FOR ALL POSSIBILITIES IS ALWAYS EQUAL TO 1, BECAUSE SOMETHING IS BOUND TO HAPPEN



Let us extrapolate to the general case: we toss n coins in the air (or we toss one coin n times)

P(x;n) = probability that exactly x of these coin will land heads up, without distinguishing which of the coins actually belongs to which group

X must be an integer for any physical experiment, but we can consider the probability to be smoothly varying with x as a continuous variable for mathematical purposes





If n coins are tossed:

- 2ⁿ different possible ways in which they can land (each coin has two possible orientations)
- Each of these possibilities is equally probable \rightarrow the probability for any of these possibilities is $1/2^n$

How many of these possibilities will contribute to our observation of x coins with heads up?

Box 1 (x): heads up Box 2 (n-x): tails up

1. How many *permutations* of the coins result in the proper separation of the x in one box, and n-x in the other?

Total number of choices for coins to fill the x slots in the heads box is $Pm(n,x) = n(n-1)(n-2) \dots (n-x+2)(n-x+1)$

more easily written as

$$\mathsf{Pm}(\mathsf{n},\mathsf{x}) = \frac{\mathsf{n}!}{(\mathsf{n}-\mathsf{x})!}$$



But we care only on which is heads up or tails up, not which landed first! We must consider contributions different only if there are different coins in the two boxes, nor if the x coins within the heads box are permuted into different time orderings!

 the number of different combinations C(n,x) of the permutations results from combining the x! different ways in which x coins in the heads box can be permuted within the box.

 $x! \rightarrow$ degeneracy factor of the permutations

$$C(n,x) = \frac{Pm(n,x)}{x!} = \frac{n!}{x!(n-x)!} = {n \choose x}$$

This is the number of different possible combinations of n items, taken x at a time

With coins: p(heads up) = p(tails up)Then: $P(x,n) = all combinations x probability of each combination = <math>C(n,x) \times 1/2^n$

GENERAL CASE:

n independent experiments (Bernoulli trials) Bernoulli trial is a random experiment in which there are only two possible outcomes: success and failure

p = probability of success of any given trial

q = (1-p) = probability of failure

Therefore the probability of x times success (heads up) and n-x failures (tails up) is p^xq^{n-x}





From the definition of p and q, the probability $P_B(x;n,p)$ for observing x of the n items to be in the state with probability p is given by the **binomial distribution**

$$P_{B}(x;n,p) = {\binom{n}{x}} p^{x} q^{n-x} = \frac{n!}{x!(n-x)!} p^{x} (1-p)^{n-x}$$

Name: the coefficients $P_B(x;n,p)$ are closely related to the binomial theorem: $n = \frac{1}{2}$

$$(p+q)^n = \sum_{x=0}^n \left[\binom{n}{x} p^x q^{n-x} \right]$$

The (j+1)th term (corresponding to x=j) of the expansion is equal to $P_B(j;n,p)$. This proves the **NORMALIZATION** of the binomial distr.



The mean of the binomial distribution is:

$$\mu = \sum_{x=0}^{n} \left[x \frac{n!}{x!(n-x)!} p^{x} (1-p)^{n-x} \right] = np$$

If we perform an experiment with n items and observe the number x of successes, after a large number of repetitions the average \vec{x} of the number of successes will approach a mean value μ given by the probability for success of each item (p) times the number of items (n)

The variance is:

$$\sigma^{x} = \sum_{x=0}^{n} \left[(x-\mu)^{2} \frac{n!}{x!(n-x)!} p^{x} (1-p)^{n-x} \right] = np(1-p)$$



If the probability for a single success p is equal to the probability for failure p = q = 1/2, then the distribution is **symmetric** about the mean μ . The median and the most probable value are both equal to the mean. The variance σ^2 is equal to half the mean: $\sigma^2 = \mu/2$ If p and q are not equal, the distribution is **asymmetric** with a smaller variance Wahrscheinlichkeit



The binomial distribution - Examples





DECAYS: observe n decays of W[±], the number x of which are $W \rightarrow \mu v$ is a binomial random variable. p = **branching ratio**



A test consists of 10 multiple choice questions with five choices for each question. As an experiment, you GUESS on each and every answer without even reading the questions.

What is the probability of getting **exactly 6** questions correct on this test?

Bits are sent over a communication channel in packets of 12. If the probability of a bit being corrupted over this channel is 0.1 and such errors are independent, what is the probability that no more than 2 bits in a packet are corrupted?

If 6 packets are sent over the channel, what is the probability that at least one packet will contain 3 or more corrupted bits?

Let X denote the number of packets containing 3 or more corrupted bits. What is the probability that X will exceed its mean by more than 2 standard deviations? Like binomial but now m outcomes instead of two. Probabilities are:

$$\vec{p} = (p_{1,...}, p_m)$$
 with $\sum_{i=1}^{m} p_i = 1$

For n trials, we want the probability to obtain:

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x_1 of outcome 1,
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x_2 of outcome 2,
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. . .

 x_m of outcome m

This is the multinomial distributions for $\vec{x} = (x_{1}, x_{2}, ..., x_{m})$

$$\mathsf{P}_{\mathsf{B}}(\vec{x};n,\vec{p}) = \frac{n!}{x_1!x_2!...x_m!} p_1^{x_1} p_2^{x_2} ... p_m^{x_m}$$



Now consider the outcome i as "success", all others as "failure" \rightarrow all x_i individually binomial with parameters n, p_i Then:

$$E[x_i] = np_i$$
 $V[x_i] = np_i(1-p_i)$

One can also find the covariance to be:

$$V_{ij} = np_i \left(\delta_{ij} - p_j \right)$$

EXAMPLE: $\vec{x} = (x_{1,}..., x_{m})$ represents a **histogram** with m bins, n total entries, all entries independent



You flipped 2 coins of type US \$1 - George Washington:

Consider a binomial x in the limit:

$$n \to \infty$$

$$p \to 0$$

$$E[x] = \mu = np \to v$$

When the average number of successes is much smaller than the possible number: µ«n because p«1

Approximation of the binomial distribution

→ POISSON DISTRIBUTION

$$P_{P}(\mathbf{x}; v) = \frac{v^{\mathbf{x}}}{\mathbf{x}!} e^{-v} \quad (\mathbf{x} \ge 0)$$
$$E[\mathbf{x}] = v, \quad V[\mathbf{x}] = v$$

Often in these experiments, neither the number n of possible events nor the probability p for each is known. What may be known is the the average number of events μ expected in each time interval.

Poisson distribution

Properties:

- Since this is an approximation to the binomial distribution, and p«1, the Poisson distribution is asymmetric about its mean
- It does not become 0 for x=0
- It is not defined for x<0

EXAMPLE: NUMBER OF EVENTS FOUND

Given a cross section σ , and a fixed integrated luminosity, with

$$v = \sigma \int L dt$$







The number of industrial injuries per working week in a particular factory is known to follow a Poisson distribution with mean 0.5

Find the probability that:

- In a particular week there will be
 - Less than 2 accidents
 - More than 2 accidents
- In a three week period there will be no accidents

The mean number of bacteria per millimetre of a liquid is known to be 4. Assuming that the number of bacteria follows a Poisson distribution, find the probability that, in 1ml of liquid, there will be

(a) no bacteria

- (b) 4 bacteria
- (c) less than 3 bacteria

Find the probability that

- (i) in 3ml of liquid there will be less than 2 bacteria
- (ii) in 0.5ml of liquid there will be more than 2 bacteria



Consider a continuous random variable x, with $-\infty < x < \infty$ Uniform pdf is:



EXAMPLE: for
$$\pi^0 \rightarrow \gamma\gamma$$
, $E\gamma$ is uniform is $[E_{\min}, E_{\max}]$, with
 $E_{\min} = \frac{1}{2}E_{\pi}(1-\beta), \quad E_{\max} = \frac{1}{2}E_{\pi}(1+\beta)$

The exponential distribution for the continuous random variable x is defined by: $2 \sqrt{1}$

EXAMPLE:

Proper decay time t of an unstable particle

$$f(t;r) = \frac{1}{\tau}e^{-t/\tau}$$
 (τ = mean lifetime)

0

1

2

3

х

4

5

Lack of memory: UNIQUE TO EXPONENTIAL

$$f(t-t_0|t \ge t_0) = f(t)$$



The Gaussian (normal) pdf for a continuous random variable is defined by:



If y~Gaussian with μ , σ^2 , then $z=(y-\mu)/\sigma$ follows $\varphi(z)$

For n independent random variables x_i with finite variances σ_i^2 , otherwise arbitrary pdf's, consider the sum:

$$y = \sum_{i=1}^{n} x_i$$

In the limit $n \rightarrow \infty$, y is a Gaussian random variable with:

$$\mathsf{E}[\mathsf{y}] = \sum_{i=1}^{n} \mu_i \qquad \mathsf{V}[\mathsf{y}] = \sum_{i=1}^{n} \sigma_i^{\mathsf{x}}$$

Almost any random variable that is a sum of a large number of small contributions, follows a Gaussian distribution.

Measurement errors are often the sum of many contributions, so frequently measured values can be treated as Gaussian r.v.s





For the proof, see book by Cowan e.g.

For finite n, the theorem is approximately valid to the extent that the fluctuation of the sum is not dominated by one (or few) terms

Beware of measurement errors with non-Gaussian tails !!!

Good example: velocity components v_x of air molecules

Medium good example: total deflection due to multiple Coulomb scattering (rare large angle deflections give non-Gaussian tail!!)

Bad example: energy loss of charged particle traversing thin gas layer (rare collisions make up large fraction of energy loss! \rightarrow Landau pdf)



The chi-square distribution for the continuous random variable $z (z \ge 0)$ is defined by:

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$$f(z;n) = \frac{1}{2^{n/2}\Gamma(n/2)} z^{n/2-1} e^{-z/2}$$

$$i = 1, 2, ... = number of degrees of freedom (dof)$$

$$E[z] = n, \quad V[z] = 2n$$

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$$i = 1, 2, ... = number of degrees of f$$

EXAMPLE: goodness-of-fit test variable especially in conjunction with method of least squares (soon!)

Z.

The Cauchy pdf for the continuous random variable x is defined by

$$f(x) = \frac{1}{\pi} \frac{\vartheta}{1+x^2}$$

This is a special case of the Breit-Wigner pdf:

$$f(\mathbf{x}; \Gamma, \mathbf{x}_0) = \frac{1}{\pi} \frac{\Gamma/2}{\Gamma'/\xi + (\mathbf{x} - \mathbf{x}_0)'}$$

E[x] not well defined, V[x] $\rightarrow \infty$ x₀ = mode (most probable value) F= full width at half maximum







Describes the energy loss Δ of a charged particle with β =v/c traversing a layer of matter of thickness d

L. Landau, J. Phys. USSR 8 (1944) 201; see also W. Allison and J. Cobb, Ann. Rev. Nucl. Part. Sci. 30 (1980) 253.







Long Landau tail

Mode (most probable value) is sensitive to $\boldsymbol{\beta}$

 \rightarrow particle identification!



$$f(\mathbf{x};\alpha,\beta) = \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} \mathbf{x}^{\alpha-1} (1-\mathbf{x})^{\beta-1}$$

$$E[\mathbf{x}] = \frac{\alpha}{\alpha+\beta}$$

$$V[\mathbf{x}] = \frac{\alpha\beta}{(\alpha+\beta)^2(\alpha+\beta+1)}$$
Often used to represent pdf of continuous random variable non-zero only between finite limits



Often used to represent pdf of continuous random variable non-zero only in $[0,\infty]$

Also similar to the gamma distribution:

- Sum of n exponential r.v.s
- Time until the nth event in Poisson process





Student's t distribution



- v = number of degrees of freedom (not necessarily integer)
- v = 1 gives Cauchy
- $\nu \to \infty$ gives Gaussian









The student's t provides a **bell-shaped pdf with adjustable tails**, ranging

- from those of a Gaussian, which fall off very quickly (v → ∞, but in fact very Gauss-like for v = two dozen)
- To the very long-tailed Cauchy (v = 1)

Developed in 1908 by William Gosset, who worked under the pseudonym "Student" for the Guiness Brewery





• Error propagation

- Monte Carlo methods
 - Transformation method
 - Integration
- Monte Carlo for particle / nuclear physics
 - Event generators
 - Detector simulation