# Statistical Methods in Particle Physics 

## Lecture 3

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## Outline

## This lecture:

- Short revision of:
- Probability density function
- Cumulative distribution function
- Functions of random variables
- Expectation values
- Covariance, correlation
- Error propagation

Next time:

- Catalog of pdf's


## Random variables

Typical example: throwing two dices

- Result of each "experiment":
$\{11,12,13,14,15,16,21,22, \ldots, 63,64,65,66\}$
- Random variable $x=$ sum of dices
$\rightarrow$ possible values (discrete!): $x_{i}=2,3,4, \ldots, 11,12$
- Probability for each value $\mathrm{x}_{\mathrm{i}}$

$\sum_{\mathrm{i}} \mathrm{P}\left(\mathrm{x}_{\mathrm{i}}\right)=1$


Cumulative distribution $\mathrm{u}(\mathrm{x})$ : probability to observe x or smaller value

## Discrete and continuous

One more example: age of a rented car (x)

| Age (Years) | $0-1$ | $1-2$ | $2-3$ | $3-4$ | $4-5$ | $5-6$ | $6-7$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Probability | .10 | .26 | .28 | .20 | .11 | .04 | .01 |

The histogram of probabilities can be described by a function $f$


$f(x)$ is called probability density function.
The domain of $f$ is the whole range of values which $x$ can take.
We use it to calculate the probability of the given variable $x$ to be in an interval [a,b]

## Discrete and continuous

## Probability for the rental car to have age between 0 and 4 years:




## Probability density functions

Suppose outcome of experiment is continuous value x :

$$
\begin{gathered}
P(x \text { found in }[x, x+d x])=f(x) d x \\
\rightarrow f(x)=\text { probability density function (pdf) }
\end{gathered}
$$

With:

$$
\begin{array}{ll}
\int_{-\infty}^{\infty} f(x) d x=1 & \begin{array}{l}
\text { Normalization } \\
\text { (x must be somewhere) }
\end{array}
\end{array}
$$

Note:

- $f(x) \geq 0$
- $f(x)$ is NOT a probability ! It has dimension $1 / x$ !


## Exercises

1. For what constant $k$ is $f(x)=k e^{-x}$ a probability density function on $[0,1]$ ?

If $f$ is any non-negative function with domain some interval ( $a, b$ ), then the process of choosing a suitable constant $k$ to make $\int_{a}^{b} k f(x) d x=1$ is called normalizing the function $f$
2. Suppose that you spin the dial shown in the figure so that it comes to rest at a random position. Model this with a suitable probability density function, and use it to find the probability that the dial will land somewhere between $5^{\circ}$ and $300^{\circ}$.


The uniform density function on the interval $[a, b]$ is the constant function defined by $f(x)=\frac{1}{b-a}$

## Cumulative distribution function (cdf)

Given a pdf $f\left(x^{\prime}\right)$, probability to have outcome less then or equal to $x$, is:

$$
\int_{-\infty}^{x} f\left(x^{\prime}\right) d x^{\prime}=F(x)
$$

Cumulative
distribution function



## Cumulative distribution function (cdf)

## $$
\int_{-\infty}^{x} f\left(x^{\prime}\right) d x^{\prime}=F(x)
$$ <br> Cumulative distribution function




- $F(x)$ is a continuously non-decreasing function
- $F(-\infty)=0, F(\infty)=1$
- For well behaved distributions:

$$
\operatorname{pdf}: \quad f(x)=\frac{\partial F(x)}{\partial x}
$$

## Exercise

1. Given the probability density function:

$$
f(x)= \begin{cases}|1-x| & \text { for } x \text { in }[0,2] \\ 0 & \text { elsewhere }\end{cases}
$$

- compute the cdf $\mathrm{F}(\mathrm{x})$
- what is the probability to find $x>1.5$ ?
- what is the probability to find $x$ in $[0.5,1]$ ?


## DONE

- T-Shirts The age (in years) of randomly chosen T-shirts in your wardrobe from last summer is distributed according to the density function $f(x)=10 / 9 x^{2}$ with $1 \leq x \leq 10$. Find the probability that a randomly chosen T -shirt is between 2 and 8 years old.
- The Doomsday Meteor The probability that a "doomsday meteor" will hit the earth in any given year and release a billion megatons or more of energy is on the order of 0.00000001 . If $X$ is the year in which a doomsday meteor hits the earth, then it may be modeled with an associated probability density function given by $f(x)=a e^{-a x}$ with $a=000000001$.
(a) What is the probability that the earth will be hit by a doomsday meteor at least once during the next 100 years? (Give the answer correct to 2 significant digits.)
(b) What is the probability that the earth has been hit by a doomsday meteor at least once since the appearance of life (about 4 billion years ago)?


## Multivariate distributions

## $\mathrm{f}(\mathrm{x}, \mathrm{y})$

The outcome of the experiment is characterized by more than 1 quantity, e.g. by $x$ and $y$

$$
P(A \cap B)=f(x, y) d x d y
$$

## Joint pdf

Normalization:

$$
\begin{aligned}
& \iint f(x, y) d x d y=1 \\
& \iint \ldots \int f\left(x_{1}, x_{2, .} . . x_{n}\right) d x_{1} d x_{2 . .} d x_{n}=1
\end{aligned}
$$

## Exercise

Let X and Y have the joint probability density function

$$
\begin{aligned}
& \qquad f(x, y)=\frac{3}{2} x^{2}(1-y) \quad \text { for }-1<x<1,-1<y<1 \\
& \text { Let } A=\{(x, y) \text { : } 0<x<1,0<y<x\} \\
& \text { Find the probability that }(X, Y) \text { falls in } A \text {. }
\end{aligned}
$$

## Marginal pdf's

From a multivariate distribution

$$
f(x, y) d x d y
$$

(e.g. scatter plot) we might be in interested only in the pdf of ONE of the components ( x or y , here)
$\rightarrow$ projection of joint pdf onto individual axes Marginal pdf

$$
\begin{aligned}
f_{x}(x) & =\int f(x, y) d y \\
f_{y}(y) & =\int f(x, y) d x
\end{aligned}
$$



Distribution of a single variable which is part of a multivariate distribution

## Conditional pdf

Recall the conditional probability:

$$
P(B \mid A)=\frac{P(A \cap B)}{P(A)}=\frac{f(x, y) d x d y}{f_{x}(x) d x}
$$

We define:

$$
\begin{aligned}
& h(y \mid x)=\frac{f(x, y)}{f_{x}(x)} \\
& g(x \mid y)=\frac{f(x, y)}{f_{y}(y)}
\end{aligned}
$$

## Conditional probability density functions

Bayes' theorem becomes: $\quad g(x \mid y)=\frac{h(y \mid x) f_{x}(x)}{f_{y}(y)}$
Recall: A, B independent if

$$
P(A \cap B)=P(A) P(B)
$$

Then: $x, y$ independent if $\quad f(x, y)=f_{x}(x) f_{y}(y)$

## Conditional pdf (2)

Example: joint pdf $f(x, y)$ is used to find the conditional pdf's

$$
\mathrm{h}\left(\mathrm{y} \mid \mathrm{x}_{1}\right) \text { and } \mathrm{h}\left(\mathrm{y} \mid \mathrm{x}_{2}\right)
$$




Basically treat some of the random variables as constant, then divide the joint pdf by the marginal pdf of those variables being held constant $\rightarrow$ so that what is left has the correct normalization $\int h(y \mid x) d y=1$

## Exercise

A soda machine has a random amount $\mathrm{Y}_{2}$ gallons of soda at the beginning of the day and dispenses $\mathrm{Y}_{1}$ gallons over the course of the day (which must be less than or equal to $\mathrm{Y}_{2}$ ). The two variables have the following joint density:

$$
f\left(y_{1}, y_{2}\right)=\left\{\begin{array}{l}
\frac{1}{2}, 0 \leq y_{1} \leq y_{2} \leq 2 \\
0 \text { elsewhere }
\end{array}\right.
$$

Find the conditional density of $\mathrm{Y}_{1}$ given $\mathrm{Y}_{2}=\mathrm{y}_{2}$ and the probability that less than $1 / 2$ gallon will be sold if the machine has 1.5 gallon at the start of the day.

## Functions of a random variable

A function of a random variable is itself a random variable.
Suppose $x$ follows a pdf $f(x)$, consider a function $a(x)$.
What is the pdf $\mathrm{g}(\mathrm{a})$ ?

$$
g(a) d a=\int_{d S} f(x) d x
$$

dS = region of $x$ space for which $a$ is in [a, a+da].

For one-variable case with unique inverse this is simply:

$g(a) d a=\left|\int_{x(a)}^{x(a+d a)} f\left(x^{\prime}\right) d x^{\prime}\right|=\int_{x(a)}^{\left.x(a)+\frac{d x}{d a} \right\rvert\, d a} f\left(x^{\prime}\right) d x^{\prime} \quad g(a)=f(x(a))\left|\frac{d x}{d a}\right|$

## Functions without unique inverse

If inverse of $a(x)$ not unique, include all dx intervals in dS which correspond to da:

Example: $a=x^{2}, \quad x= \pm \sqrt{a}, \quad d x= \pm \frac{d a}{2 \sqrt{a}}$

$g(a) d a=\int_{d S} f(x) d x$
$d S=\left[\sqrt{a}, \sqrt{a}+\frac{d a}{2 \sqrt{a}}\right] \cup\left[-\sqrt{a}-\frac{d a}{2 \sqrt{a}},-\sqrt{a}\right]$
$g(a)=\frac{f(\sqrt{a})}{2 \sqrt{a}}+\frac{f(-\sqrt{a})}{2 \sqrt{a}}$

## Functions of more than one random variable

Consider the random variables $\vec{x}=\left(x_{1}, x_{2}, \ldots, x_{n}\right)$
And the function $\quad a(\vec{x})$

Its probability density function is:

$$
g\left(a^{\prime}\right) d a^{\prime}=\int \ldots \int_{d S} f\left(x_{1, .} . ., x_{n}\right) d x_{1 .} . . d x_{n}
$$

$d S=$ region of $\quad \vec{x}$ space between (hyper)surfaces defined by:

$$
a(\vec{x})=a^{\prime}, a(\vec{x})=a^{\prime}+d a^{\prime}
$$

## Example

Consider the random variables $x, y>0$, which follow the joint $p d f f(x, y)$. Consider the function $z=x y$. What is its pdf $g(z)$ ?

$$
\begin{aligned}
g(z) d z & =\int \ldots \int_{d S} f(x, y) d x d y \\
& =\int_{0}^{\infty} d x \int_{z / x}^{(z+d z) / x} f(x, y) d y \\
g(z) & =\int_{0}^{\infty} f\left(x, \frac{z}{x}\right) \frac{d x}{x} \\
& =\int_{0}^{\infty} f\left(\frac{z}{y}, y\right) \frac{d y}{y}
\end{aligned}
$$

Mellin convolution


## More on transformation of variables

Consider a random vector $\vec{x}=\left(x_{1}, \cdots, x_{n}\right)$ with joint pdf $f(\vec{x})$.
Form $n$ linearly independent functions $\vec{y}(\vec{x})=\left(y_{1}(\vec{x}), \ldots, y_{n}(\vec{x})\right)$ for which the inverse functions $x_{1}(\vec{y}), \ldots, x_{n}(\vec{y})$ exist.

The joint pdf of the vector of functions is $g(\vec{y})$ Is

$$
g(\vec{y})=|J| f(\vec{x})
$$

where J is the Jacobian
determinant:

$$
J=\left|\begin{array}{cccc}
\frac{\partial x_{1}}{\partial y_{1}} & \frac{\partial x_{1}}{\partial y_{2}} & \cdots & \frac{\partial x_{1}}{\partial y_{n}} \\
\frac{\partial x_{2}}{\partial y_{1}} & \frac{\partial x_{2}}{\partial y_{2}} & \cdots & \frac{\partial x_{2}}{\partial y_{n}} \\
\vdots & & & \vdots \\
& & \cdots & \frac{\partial x_{n}}{\partial y_{n}}
\end{array}\right|
$$

## Expectation value

Consider a continuous random variable $x$ with pdf $f(x)$.
Define expectation (mean) value as

$$
E[x]=\int x f(x) d x
$$

$\mathrm{E}[\mathrm{x}]$ is NOT a function of $x$, it is rather a parameter of $f(x)$

Notation (often):

$$
\mathrm{E}[\mathrm{x}]=\mu \quad \sim \text { "centre of gravity" of pdf. }
$$

For a function $\mathrm{y}(\mathrm{x})$ with $\operatorname{pdf} \mathrm{g}(\mathrm{y})$,

$$
E[y]=\int y g(y) d y=\int y(x) f(x) d x
$$

(equivalent)

## Variance and standard deviation

## Variance:

$$
\mathrm{V}[\mathrm{x}]=\mathrm{E}\left[(\mathrm{x}-\mathrm{E}[\mathrm{x}])^{2}\right]=\mathrm{E}\left[\mathrm{x}^{\top}\right]-\mu^{\curlyvee}
$$

Notation: $\quad \mathrm{V}[\mathrm{x}]=\sigma^{2}$
Standard deviation: $\sigma=\sqrt{\sigma^{2}} \quad$ Same dimension as x


## Exercises

- Find the mean of the random variable $X$ that has probability density function $f$ given by:
$f(x)=x^{2} / 3$ for $-1<x<2$
- Suppose that X has the power distribution with parameter $\mathrm{a}>1$, which has density:

$$
f(x)=(a-1) x^{-a} \quad \text { for } x>1
$$

Show that:

$$
E[x]=\left\{\begin{array}{l}
\infty, \text { if } 1<a \leq 2 \\
\frac{a-1}{a-2}, \text { if } a>2
\end{array}\right.
$$

- Let the random variable $x$ have the probability density function $f(x)=\left\{\begin{array}{c}3 x^{2} \text { if } 0 \leq x \leq 1 \\ 0, \text { elsewhere }\end{array}\right.$

Calculate its variance.

## Covariance and correlation

Define covariance $\operatorname{cov}[x, y]$ (also use matrix notation $V_{x y}$ ) as:

$$
\operatorname{cov}[\mathrm{x}, \mathrm{y}]=\mathrm{E}\left[\left(\mathrm{x}-\mu_{\mathrm{x}}\right)\left(\mathrm{y}-\mu_{\mathrm{y}}\right)\right]
$$

Can be written as:

$$
\operatorname{cov}[\mathrm{x}, \mathrm{y}]=\mathrm{E}[\mathrm{xy}]-\mu_{\mathrm{x}} \mu_{\mathrm{y}}
$$

Correlation coefficient (dimensionless) defined as:

$$
\rho_{\mathrm{xy}}=\frac{\operatorname{cov}[\mathrm{x}, \mathrm{y}]}{\sigma_{\mathrm{x}} \sigma_{\mathrm{y}}}, \quad-1 \leq \rho_{\mathrm{xy}} \leq+1
$$

## Correlation coefficient

$\rho=0.75$


$$
\rho=-0.75
$$

$$
\rho=0.25
$$

## Independent variables

If $x$ and $y$ are independent, i.e. $f(x, y)=f_{x}(x) f_{y}(y)$, then:

$$
E[x y]=\iint x y f(x, y) d x d y=\mu_{x} \mu_{y}
$$

Therefore:

$$
\operatorname{cov}[x, y]=0
$$

$x$ and $y$ are 'uncorrelated'

Note!! The converse is NOT always true!!!

## Exercise

Let $[\mathrm{xy}$ ] be an absolutely continuous random vector with domain:

$$
R_{X Y}=\{(x, y): 0 \leq x \leq y \leq 2\}
$$

i.e. $R_{x y}$ is the set of all couples ( $x, y$ ) such that $0 \leq y \leq 2$ and $0 \leq x \leq y$. Let the joint probability density function of $[x y]$ be:

$$
f(x, y)=\left\{\begin{array}{cc}
\frac{3}{8} y, & \text { if }(x, y) \in R_{X Y} \\
0 & , \text { otherwise }
\end{array}\right.
$$

Compute the covariance between X and Y .

## Error propagation

Suppose we measure a set of values $\overrightarrow{\mathrm{x}}=\left(\mathrm{x}_{1}, \ldots, \mathrm{x}_{\mathrm{n}}\right)$
which follow some joint pdf $f(\vec{x})$.
$f(\vec{x})$ might be not fully known. But we have the covariances:
$\mathrm{V}_{\mathrm{ij}}=\operatorname{cov}\left[\mathrm{x}_{\mathrm{i}}, \mathrm{x}_{\mathrm{j}}\right]$, and the means $\vec{\mu}=\mathrm{E}[\overrightarrow{\mathrm{x}}] \quad$ (in practice only estimates)

Now consider a function $\mathrm{y}(\overrightarrow{\mathrm{x}})$.
What is the variance of $y(\vec{x})$ ?
Hard way: use joint pdf $f(\vec{x})$ to find the pdf $g(y)$,
Then from $g(y)$ find

$$
V[y]=E\left[y^{2}\right]-(E[y])^{2}
$$

Often NOT practical. $f(\vec{x})$ may not even be fully known ...

## Error propagation - 2

Expand $\mathbf{y}(\overrightarrow{\mathrm{x}})$ to the first order in a Taylor series about $\vec{\mu}$

$$
\mathrm{y}(\overrightarrow{\mathrm{x}}) \approx \mathrm{y}(\vec{\mu})+\sum_{\mathrm{i}=1}^{\mathrm{n}}\left[\frac{\partial \mathrm{y}}{\partial \mathrm{x}_{\mathrm{i}}}\right]_{\overrightarrow{\mathrm{x}}=\vec{\mu}}\left(\mathrm{x}_{\mathrm{i}}-\mu_{\mathrm{i}}\right)
$$

To find the variance $V[y]$ we need $E\left[y^{2}\right]$ and $E[y]$ :

$$
\mathrm{E}[\mathrm{y}(\overrightarrow{\mathrm{x}})] \approx \mathrm{y}(\vec{\mu}) \quad \text { since } \quad \mathrm{E}\left[\mathrm{x}_{\mathrm{i}}-\mu_{\mathrm{i}}\right]=0
$$

## Error propagation - 3

$$
\begin{gathered}
\mathrm{E}\left[\mathrm{y}^{2}(\overrightarrow{\mathrm{x}})\right] \approx \mathrm{y}^{2}(\vec{\mu})+2 \mathrm{y}(\vec{\mu}) \sum_{\mathrm{i}=1}^{\mathrm{n}}\left[\frac{\partial \mathrm{y}}{\partial \mathrm{x}_{\mathrm{i}}}\right]_{\overrightarrow{\mathrm{x}}=\vec{\mu}} \mathrm{E}\left[\mathrm{x}_{\mathrm{i}}-\mu_{\mathrm{i}}\right] \\
+\mathrm{E}\left[\left(\sum_{\mathrm{i}=1}^{\mathrm{n}}\left[\frac{\partial \mathrm{y}^{2}}{\partial \mathrm{x}_{\mathrm{i}}}\right]_{\overrightarrow{\mathrm{x}}=\vec{\mu}}\left(\mathrm{x}_{\mathrm{i}}-\mu_{\mathrm{i}}\right)\right)\left(\sum_{\mathrm{j}=1}^{\mathrm{n}}\left[\frac{\partial \mathrm{y}}{\partial \mathrm{x}_{\mathrm{j}}}\right]_{\overrightarrow{\mathrm{x}}=\vec{\mu}}\left(\mathrm{x}_{\mathrm{j}}-\mu_{\mathrm{j}}\right)\right)\right] \\
=\mathrm{y}^{2}(\vec{\mu})+\sum_{\mathrm{i}, \mathrm{j}=1}^{\mathrm{n}}\left[\frac{\partial \mathrm{y}}{\partial \mathrm{x}_{\mathrm{i}}} \frac{\partial \mathrm{y}}{\partial \mathrm{x}_{\mathrm{j}}}\right]_{\overrightarrow{\mathrm{x}}=\vec{\mu}} V_{\mathrm{ij}}
\end{gathered}
$$

Putting the ingredients together gives the variance of $y(\vec{x})$

$$
\sigma_{y}^{2} \approx \sum_{i, j=1}^{\mathrm{n}}\left[\frac{\partial \mathrm{y}}{\partial \mathrm{x}_{\mathrm{i}}} \frac{\partial \mathrm{y}}{\partial \mathrm{x}_{\mathrm{j}}}\right]_{\overrightarrow{\mathrm{x}}=\vec{\mu}} \mathrm{V}_{\mathrm{ij}}
$$

## Error propagation - 4

If the $\mathrm{x}_{\mathrm{i}}$ are uncorrelated, i.e. $\mathrm{V}_{\mathrm{ij}}=\sigma_{i}^{2} \delta_{\mathrm{ij}}$, then this becomes:

$$
\sigma_{\mathrm{y}}^{2} \approx \sum_{\mathrm{i}=1}^{\mathrm{n}}\left[\frac{\partial \mathrm{y}}{\partial \mathrm{x}_{\mathrm{i}}}\right]_{\overrightarrow{\mathrm{x}}=\vec{\mu}}^{2} \sigma_{\mathrm{i}}^{2}
$$

Similar for a set of $m$ functions $\quad \vec{y}(\vec{x})=\left(y_{1}(\vec{x}), \ldots, y_{m}(\vec{x})\right)$

$$
\mathrm{U}_{\mathrm{kl}}=\operatorname{cov}\left[\mathrm{y}_{\mathrm{k}}, \mathrm{y}_{1}\right] \approx \sum_{\mathrm{i}, \mathrm{j}=1}^{\mathrm{n}}\left[\frac{\partial \mathrm{y}_{\mathrm{k}}}{\partial \mathrm{x}_{\mathrm{i}}} \frac{\partial \mathrm{y}_{\mathrm{l}}}{\partial \mathrm{x}_{\mathrm{j}}}\right] \mathrm{V}_{\mathrm{x}=\vec{\mu}} \mathrm{V}_{\mathrm{ij}}
$$

Or in matrix notation $U=A \vee A^{\top}$, where $A_{i j}=\left[\frac{\partial y_{i}}{\partial x_{j}}\right]_{\vec{x}=\vec{\mu}}$

## Error propagation - 5

These are the error propagation formulae: the covariances which summarize the "errors" in measurements of $\vec{x}$, are propagated to the new quantities $\overrightarrow{\mathrm{y}}(\overrightarrow{\mathrm{x}})$

## LIMITATION:



Exact only if $\vec{y}(\vec{x})$ linear.
Approximation breaks down if function is nonlinear over a region comparable in size to the $\sigma_{i}$
N.B. We said nothing about the pdf of the $x_{i}$,

e.g. it does not have to be Gaussian

## Error propagation: SPECIAL CASES

$$
\begin{aligned}
& \mathrm{y}=\mathrm{x}_{1}+\mathrm{x}_{2} \rightarrow \sigma_{\mathrm{y}}^{2}=\sigma_{1}^{2}+\sigma_{2}^{2}+2 \operatorname{cov}\left[\mathrm{x}_{1}, \mathrm{x}_{2}\right] \\
& \mathrm{y}=\mathrm{x}_{1} \mathrm{x}_{2} \rightarrow \frac{\sigma_{\mathrm{y}}^{2}}{\mathrm{y}^{2}}=\frac{\sigma_{1}^{2}}{\mathrm{x}_{1}^{2}}+\frac{\sigma_{2}^{2}}{\mathrm{x}_{2}^{2}}+2 \frac{\operatorname{cov}\left[\mathrm{x}_{1}, \mathrm{x}_{2}\right]}{\mathrm{x}_{1} \mathrm{x}_{2}}
\end{aligned}
$$

That is, if the $x_{i}$ are uncorrelated:
Add errors quadratically for the sum (or difference), Add relative errors quadratically for product (or ratio)
correlations can change this completely...

## Error propagation - MORE SPECIAL

Consider $\mathrm{y}=\mathrm{x}_{1}-\mathrm{x}_{2}$ with:

$$
\begin{gathered}
\mu_{1}=\mu_{2}=10, \quad \sigma_{1}=\sigma_{2}=1, \quad \rho=\frac{\operatorname{cov}\left[\mathrm{x}_{1}, \mathrm{x}_{2}\right]}{\sigma_{1} \sigma_{2}}=0 \\
\mathrm{~V}[\mathrm{y}]=1^{2}+1^{2}=2 \rightarrow \sigma_{\mathrm{y}}=1.4
\end{gathered}
$$

Now suppose $\rho=1$ (full correlation). Then:

$$
\mathrm{V}[\mathrm{y}]=1^{2}+1^{2}-2=0 \rightarrow \sigma_{y}=0
$$

i.e. for $100 \%$ correlation, the error in the difference goes to 0 !!

## Wrapping up lecture 3

- Probability density functions. Described by:
- Expectation values (mean, variance)
- Covariance
- Correlation
- Given a function of a random variable, we know how to find the variance of the function using error propagation

NEXT TIME:

- Examples of probability functions:
binomial, multinomial, Poisson, uniform, exponential, Gaussian
- Central limit theorem

Chi-square, Cauchy, Landau

