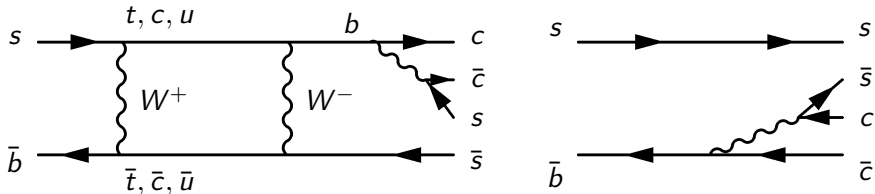




Short recap: $B_s \rightarrow J/\psi (\mu\mu) \Phi (KK)$



How can we extract $\Phi_S (= 2\beta_S) = \Phi_{SM} + \Phi_{NP} \approx \Phi_{NP}$ and $\Delta\Gamma = \Gamma_H - \Gamma_L$? \rightarrow

Maximum-Likelihood-Fit



What is a Likelihood?

Data $\{x_1, x_2, \dots, x_N\}$

x_i drawn from **Probability Density Function** $P(x_i; a)$ with Parameter a

Likelihood = Probability for data set $\{x_1, x_2, \dots, x_N\}$, product of $P(x_i; a)$

$$\begin{aligned}\mathcal{L}(x_1, \dots, x_N; a) &= P(x_1; a) \cdot P(x_2; a) \cdot \dots \cdot P(x_N; a) \\ &= \prod_{i=1}^N P(x_i; a)\end{aligned}$$

Principle of Maximum Likelihood: Find a for which \mathcal{L} is maximal

$$\frac{d}{da} \mathcal{L}(x_1, \dots, x_N; a) = 0$$

$$\frac{d}{da} \ln(\mathcal{L}) = \sum_{i=1}^N \frac{d}{da} \ln P(x_i; a) = 0 \quad (\text{used in practice})$$

Not always possible analytically \rightarrow use numerical maximisation

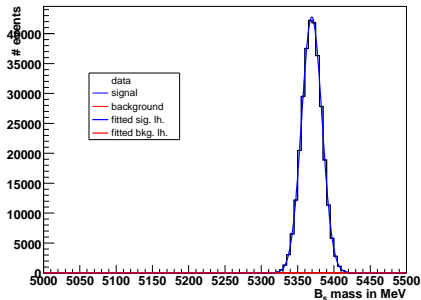


An Example: Gaussian Mass Distribution

Parameter $a = M$, Data $\{m_1, \dots, m_N\}$

$$\text{P.D.F.: } P_i = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(m_i - M)^2}{2\sigma^2}}$$

mass distribution



$$\begin{aligned} \frac{d}{dM} \ln(\mathcal{L}) &= \sum_{i=1}^N \frac{d}{dM} \ln P(m_i; M) \\ &= \sum_{i=1}^N \frac{d}{dM} \left(\ln \frac{1}{\sigma\sqrt{2\pi}} - \frac{(m_i - M)^2}{2\sigma^2} \right) \\ &= \sum_{i=1}^N \frac{m_i - M}{\sigma^2} = 0 \\ \Rightarrow M &= \frac{1}{N} \sum_{i=1}^N m_i \end{aligned}$$



What about errors?

Solve $\ln \mathcal{L}(a) = \ln \mathcal{L}_{\max} - \frac{1}{2}$ for a !

Example $P_i = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(m_i - M)^2}{2\sigma^2}}$:

$$\begin{aligned} \ln \mathcal{L}(M + \Delta M) &= \ln \mathcal{L}_{\max}(M) - \frac{1}{2} \\ \sum_{i=1}^N -\frac{(m_i - \Delta M - M)^2}{2\sigma^2} &= \sum_{i=1}^N -\frac{(m_i - M)^2}{2\sigma^2} - \frac{1}{2} \\ N \frac{\Delta M^2}{2\sigma^2} + 2N \frac{\Delta M}{2\sigma^2} M - 2\Delta M \sum_{i=1}^N m_i &= \frac{1}{2} \quad \left| \sum_i m_i = Nm_{B_s} \right. \\ \Delta M^2 &= \frac{\sigma^2}{N} \\ \Delta M &= \pm \frac{\sigma}{\sqrt{N}} \end{aligned}$$

This also works for multiple parameters \rightarrow Confidence regions



The Pros and Cons of Likelihoods

LH-Estimator (value of a for which \mathcal{L} maximal)

- is optimal (minimal Variance) for large N
- can be time-consuming to compute
- can be biased for small N !
- need to know p.d.f. shape beforehand
- χ^2 -method can be derived from ML if p.d.f.s are gaussian

Booktip: Statistics - A Guide to the Use of Statistical Methods in the Physical Sciences, R. Barlow



The Reconstructed B_s-Mass

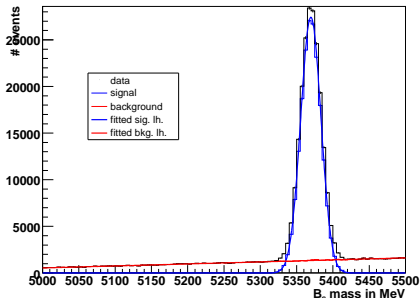
Used to separate signal/background events

For Signal: Use Gaussian peak (always normalize correctly!)

$$P_{\text{sig}}^M = \frac{1}{\sqrt{2\pi}\sigma_m} e^{-\frac{(m_i - M)^2}{2\sigma_m^2}}$$

For Background: Use Linear or Exponential distribution

mass distribution



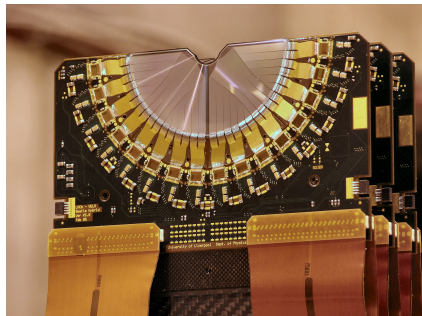
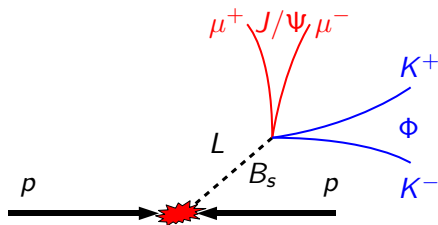
$$\mathcal{L} = \prod_i^{\text{all events}} P_i(m_i)$$

$$P_i = f_{\text{sig}} P_{\text{sig}}^M(m_i) + (1 - f_{\text{sig}}) P_{\text{bkg}}^M(m_i)$$

Depending on mass m_i , event is
Signal/Background-like

The Proper Time 1: What is the Proper Time?

Defined as $t = \frac{L}{p} m_{B_s}$, $\sigma_t = \frac{\sigma_L}{p} m_{B_s}$



Good secondary Vertex resolution needed!

→ $VE_{\text{rtex}} LO_{\text{cator}} : \sigma_{ct} = 0.03\text{ps} \approx 150\mu\text{m}$

Momentum resolution negligible



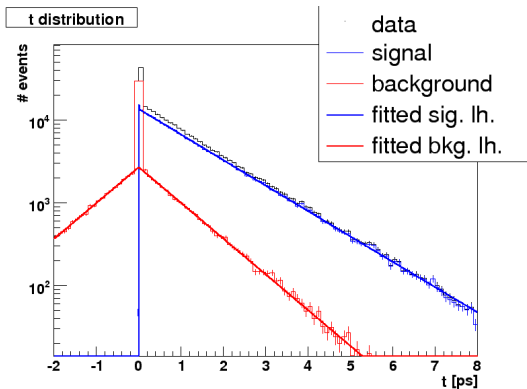
The Proper Time 2: Model

For Signal: B_s -decays

$$P_i \propto e^{-\Gamma_L t_i} \text{ or } e^{-\Gamma_H t_i}$$

For Background: Mainly prompt J/Ψ (use sideband)

$$P_i \propto \delta(t_i)$$



Not realistic

Finite decay length resolution
 \Rightarrow Finite proper time resolution!

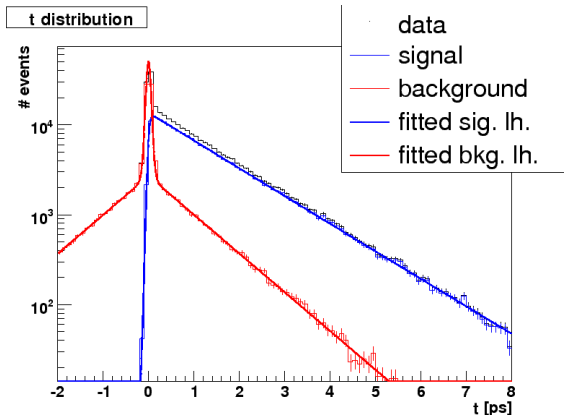


The Proper Time 3: Convolution

⇒ Need to convolute proper time probabilities with gaussian resolution

$$P_i^{\text{real}}(t) = P_i^{\text{ideal}}(t) \otimes \frac{1}{\sigma_t \sqrt{2\pi}} e^{-\frac{(t-t')^2}{2\sigma_t^2}}$$

$$\frac{1}{2} e^{-\Gamma t} e^{\frac{1}{2} \sigma_t^2 \Gamma^2} \overset{e^{-\Gamma t}}{\downarrow} \text{erfc}\left(\frac{\sigma_t \Gamma}{\sqrt{2}} - \frac{t}{\sigma_t \sqrt{2}}\right)$$





The Transversity Angles 1

Final state is an admixture of CP-eigenstates

$B_s(J=0) \rightarrow J/\Psi(J=1)\Phi(J=1) \rightarrow$ final state $L=0,1,2$

$$CP(J/\Psi\Phi) = CP(J/\Psi)CP(\Phi)(-1)^L = (-1)^L$$

L	CP	Decay Amplitude
0	even	A_{\parallel}
1	odd	A_{\perp}
2	even	A_0

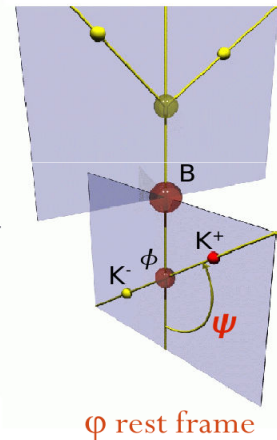
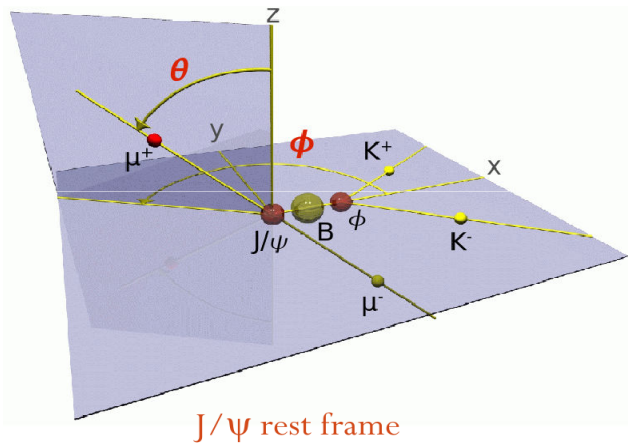
Angular analysis for separation of final state

Need 3 angles to describe the final state

→ **Transversity Base** $\vec{\rho} = (\Theta, \Psi, \Phi)$

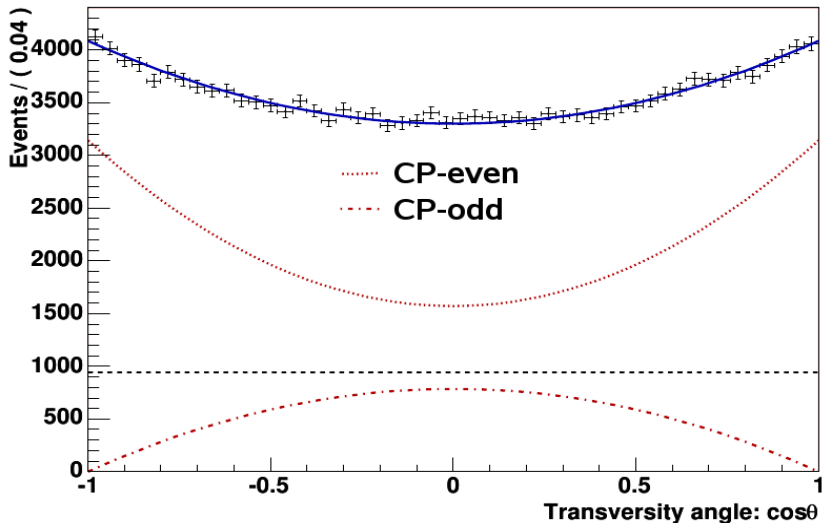


The Transversity Angles 2



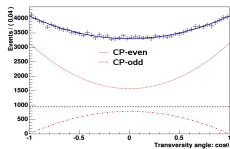
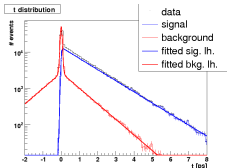
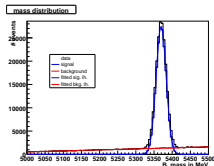


The Transversity Angles 3: Separation





Now Put Everything Together



Measured Quantities per event: $m_i, t_i, \vec{\rho}_i = (\Theta_i, \Psi_i, \Phi_i)$

Physical Parameters: $\Phi_s, \Gamma, \Delta\Gamma, |A_0|, |A_{||}|, |A_{\perp}|, \delta_1, \delta_2, \Delta m$

$$\mathcal{L}_{\text{tot}} = \prod_i^{\text{all events}} P_i$$

$$P_i = f_{\text{sig}} P_{\text{sig}} + (1 - f_{\text{sig}}) P_{\text{bkg}}$$

$$P_{\text{sig}} = P_{\text{sig}}^{t/\rho}(t_i, \vec{\rho}_i) \times P_{\text{sig}}^M(m_i)$$

$$P_{\text{bkg}} = P_{\text{bkg}}^{t/\rho}(t_i, \vec{\rho}_i) \times P_{\text{bkg}}^M(m_i)$$

Unfortunately, $P_{\text{sig}}^{t/\rho}$ cannot be separated in proper time/angles!



The Time/Angular Probability: Angular Dependence

$$P_{\text{sig}}^{t/\rho} = \underbrace{\frac{1 + \xi D}{1 + |\xi|}}_{\text{Prob. } B_s \text{ id.}} \overbrace{\sum_{k=1}^6 A_{(k)}(t_i) f_{(k)}(\vec{\rho}_i)}^{|\langle J/\psi\phi | B_s \rangle|^2} + \underbrace{\frac{1 - \xi D}{1 + |\xi|}}_{\text{Prob. } \bar{B}_s \text{ id.}} \overbrace{\sum_{k=1}^6 \bar{A}_{(k)}(t_i) f_{(k)}(\vec{\rho}_i)}^{|\langle J/\psi\phi | \bar{B}_s \rangle|^2}$$

$f_1 \dots f_6$ are only dependent on the measured angles

k	$A_{(k)}(t)$	$\bar{A}_{(k)}(t)$	$f_{(k)}(\vec{\rho})$
1	$ A_0(t) ^2$	$ \bar{A}_0(t) ^2$	$\frac{9}{32\pi} 2 \cos^2 \psi (1 - \sin^2 \Theta \cos^2 \phi)$
2	$ A_{\parallel}(t) ^2$	$ \bar{A}_{\parallel}(t) ^2$	$\frac{9}{32\pi} \sin^2 \psi (1 - \sin^2 \Theta \sin^2 \phi)$
3	$ A_{\perp}(t) ^2$	$ \bar{A}_{\perp}(t) ^2$	$\frac{9}{32\pi} \sin^2 \psi \sin^2 \Theta$
4	$\text{Im}(A_{\parallel}^*(t) A_{\perp}(t))$	$\text{Im}(\bar{A}_{\parallel}^*(t) \bar{A}_{\perp}(t))$	$-\frac{9}{32\pi} \sin^2 \psi \sin 2\Theta \sin \phi$
5	$\text{Re}(A_0^*(t) A_{\parallel}(t))$	$\text{Re}(\bar{A}_0^*(t) \bar{A}_{\parallel}(t))$	$\frac{9}{32\pi\sqrt{2}} \sin 2\psi \sin^2 \Theta \sin 2\phi$
6	$\text{Im}(A_0^*(t) A_{\perp}(t))$	$\text{Im}(\bar{A}_0^*(t) \bar{A}_{\perp}(t))$	$\frac{9}{32\pi\sqrt{2}} \sin 2\psi \sin 2\Theta \cos \phi$

Amplitudes on next slide



The Time/Angular Probability: Tagged

$$P_{\text{sig}}^{t/\rho} = \overbrace{\frac{1 + \xi D}{1 + |\xi|}}^{\text{Tagging}} \sum_{k=1}^6 A_{(k)}(t_i) f_{(k)}(\vec{\rho}_i) + \overbrace{\frac{1 - \xi D}{1 + |\xi|}}^{\text{Tagging}} \sum_{k=1}^6 \bar{A}_{(k)}(t_i) f_{(k)}(\vec{\rho}_i)$$

$$|A_0(t)|^2 = \frac{|A_0(0)|^2}{2} \left[(1 + \cos \Phi_s) e^{-\Gamma L t} + (1 - \cos \Phi_s) e^{-\Gamma H t} + 2e^{-\Gamma t} \sin(\Delta m t) \sin \Phi_s \right]$$

$$|A_{\parallel}(t)|^2 = \frac{|A_{\parallel}(0)|^2}{2} \left[(1 + \cos \Phi_s) e^{-\Gamma L t} + (1 - \cos \Phi_s) e^{-\Gamma H t} + 2e^{-\Gamma t} \sin(\Delta m t) \sin \Phi_s \right]$$

$$|A_{\perp}(t)|^2 = \frac{|A_{\perp}(0)|^2}{2} \left[(1 - \cos \Phi_s) e^{-\Gamma L t} + (1 + \cos \Phi_s) e^{-\Gamma H t} - 2e^{-\Gamma t} \sin(\Delta m t) \sin \Phi_s \right]$$

$$\text{Im}(A_{\parallel}^*(t) A_{\perp}(t)) = + |A_{\parallel}(0)| |A_{\perp}(0)| \left[e^{-\Gamma t} (\sin \delta_1 \cos(\Delta m t) - \cos \delta_1 \sin(\Delta m t) \cos \Phi_s) \right]$$

$$- \frac{1}{2} (e^{-\Gamma H t} - e^{-\Gamma L t}) \cos \delta_1 \sin \Phi_s$$

$$\text{Re}(A_0^*(t) A_{\parallel}(t)) = \frac{1}{2} |A_0(0)| |A_{\parallel}(0)| \cos(\delta_2 - \delta_1) \left[(1 + \cos \Phi_s) e^{-\Gamma L t} + (1 - \cos \Phi_s) e^{-\Gamma H t} + 2e^{-\Gamma t} \sin(\Delta m t) \sin \Phi_s \right]$$

$$\text{Im}(A_0^*(t) A_{\perp}(t)) = + |A_0(0)| |A_{\perp}(0)| \left[e^{-\Gamma t} (\sin \delta_2 \cos(\Delta m t) - \cos \delta_2 \sin(\Delta m t) \cos \Phi_s) \right]$$

$$- \frac{1}{2} (e^{-\Gamma H t} - e^{-\Gamma L t}) \cos \delta_2 \sin \Phi_s$$

Terms depending on Φ_s

Δm only with Tagging

2-fold ambiguity in $\Delta\Gamma$



The Time/Angular Probability: UnTagged

$$P_{\text{sig}}^{t/\rho} = \underbrace{\frac{1}{2}}_{\text{No Tagging}} \sum_{k=1}^6 A_{(k)}(t_i) f_{(k)}(\vec{\rho}_i) + \underbrace{\frac{1}{2}}_{\text{No Tagging}} \sum_{k=1}^6 \bar{A}_{(k)}(t_i) f_{(k)}(\vec{\rho}_i)$$

$$|A_0(t)|^2 = \frac{|A_0(0)|^2}{2} \left[(1 + \cos \Phi_s) e^{-\Gamma L t} + (1 - \cos \Phi_s) e^{-\Gamma H t} + 2e^{-\Gamma t} \sin(\Delta m t) \sin \Phi_s \right]$$

$$|A_{\parallel}(t)|^2 = \frac{|A_{\parallel}(0)|^2}{2} \left[(1 + \cos \Phi_s) e^{-\Gamma L t} + (1 - \cos \Phi_s) e^{-\Gamma H t} + 2e^{-\Gamma t} \sin(\Delta m t) \sin \Phi_s \right]$$

$$|A_{\perp}(t)|^2 = \frac{|A_{\perp}(0)|^2}{2} \left[(1 - \cos \Phi_s) e^{-\Gamma L t} + (1 + \cos \Phi_s) e^{-\Gamma H t} - 2e^{-\Gamma t} \sin(\Delta m t) \sin \Phi_s \right]$$

$$\begin{aligned} \text{Im}(A_{\parallel}^*(t) A_{\perp}(t)) &= +|A_{\parallel}(0)| |A_{\perp}(0)| \left[e^{-\Gamma t} (\sin \delta_1 \cos(\Delta m t) - \cos \delta_1 \sin(\Delta m t) \cos \Phi_s) \right. \\ &\quad \left. - \frac{1}{2} (e^{-\Gamma H t} - e^{-\Gamma L t}) \cos \delta_1 \sin \Phi_s \right] \end{aligned}$$

$$\text{Re}(A_0^*(t) A_{\parallel}(t)) = \frac{1}{2} |A_0(0)| |A_{\parallel}(0)| \cos(\delta_2 - \delta_1) \left[(1 + \cos \Phi_s) e^{-\Gamma L t} + (1 - \cos \Phi_s) e^{-\Gamma H t} + 2e^{-\Gamma t} \sin(\Delta m t) \sin \Phi_s \right]$$

$$\begin{aligned} \text{Im}(A_0^*(t) A_{\perp}(t)) &= +|A_0(0)| |A_{\perp}(0)| \left[e^{-\Gamma t} (\sin \delta_2 \cos(\Delta m t) - \cos \delta_2 \sin(\Delta m t) \cos \Phi_s) \right. \\ &\quad \left. - \frac{1}{2} (e^{-\Gamma H t} - e^{-\Gamma L t}) \cos \delta_2 \sin \Phi_s \right] \end{aligned}$$

Less sensitivity on Φ_s

4-fold ambiguity in $\Phi_s, \Delta\Gamma$



Toy Studies: Fit Validation

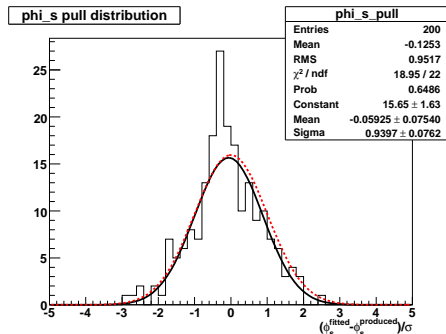
- Is the Fit biased?
- Does it under/overestimate the errors?

⇒ Do Toy Study

- 1 Create large number of simulated data samples
- 2 Run Fit on those data samples
- 3 For Parameter a Pull =


$$\frac{a_{\text{fitted}} - a_{\text{generated}}}{\Delta a_{\text{fitted}}}$$

⇒ **Expectation: Gaussian distribution with mean 0 and width 1**





(Expected) Performance Comparison

Quantity	CDF	D0	
N_{sig}	2.02k	1.97k	131k (2fb^{-1})
σ_t	0.1ps	0.1ps	0.03ps
ϵD^2	3.6% / 1.4%	4.7%	8%
$\Delta\Gamma$	$[-0.4, 0.4]\text{ps}^{-1}$	$(0.19 \pm 0.07)\text{ps}^{-1}$	$(0.10 \pm 0.008)\text{ps}^{-1}$
Φ_s	$[0.32, 2.82] / [0.40, 1.20]$	-0.57 ± 0.30	-0.04 ± 0.02



(Very) Preliminary Results

$\Delta\Phi_s$ Tagged

N_{sig}	$\Phi_s = -0.04$	$\Phi_s = -0.60$
6.4k		0.14
19.2k		0.08
180.0k	0.02	

$\Delta\Phi_s$ Untagged (δ_1, δ_2 fixed!)

N_{sig}	$\Phi_s = -0.04$	$\Phi_s = -0.60$
6.4k		
19.2k		
180.0k	0.08	